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**Some Uniqueness Conditions
and
Stability Estimates
for the Identification of Conductivity
in a Parabolic PDE**

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Advanced Modelling for Environmental Impact Assessment

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UNIQUENESS CONDITIONS: *Cauchy datum*

Hp.1 data pair $\{u, f\}, \{v, f\} \cdot \exists \cdot u_t, v_t, f \in C^0(\bar{T}; H^{-1}(D))$

and $u_x, v_x \in C^0(\bar{T}; C^0(\bar{D}))$; $v_x \neq 0, \forall (x, t) \in \bar{Q}$

Def.1 $w := v - u$ *Biblioteca*

Hp.2 $\exists \hat{a}(u, f), b(v, f) \in A_{ad}$ *Zuadrelli*

Def.2 $g := b - \hat{a}$

Hp.3 $g \in B_{ad} := \{g \mid g \in L^{\infty}(D); \exists \lim_{x \rightarrow x_0^+} g \text{ and } \lim_{x \rightarrow x_0^+} g = 0\}$ *Crosta*

Def.3 the defect $r := -w_t + (aw_x)_x$; $R := \frac{r}{v_x}$

Hp.4 properties of antiderivatives of distributions

$\{R^{[-1]}\} \subset C^0(\bar{T}; L^{\infty}(D))$; $\exists \lim_{x \rightarrow x_0^+} R^{[-1]} \forall t \in \bar{T}$

Thm. IF $\exists s \in \bar{T} \cdot \exists \cdot w(s) = w_t(s) = 0 \forall x \in D$ THEN $g = \text{a.e.} 0$ in D .

UNIQUENESS CONDITIONS:

Kitamura & Nakagiri extended*

Def. (set of points where u stationary)

$$E_u := \{y \mid y \in \bar{D}, y(\cdot) \in C^0(\bar{T}), \text{ either } u_x(y, t) = 0 \text{ or } \lim_{x \rightarrow y^\pm} u_x(y, t) = 0\}$$

$$f \in L^2(T, H^{-1}(D)); u \in \mathcal{U}_{ad}$$

Hp. $\exists \tilde{a} \in A_{ad} \cdot \exists \cdot u(\hat{a}, f) =_{a.e.} u(\tilde{a}, f)$ in Q .

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Thm.

IF

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either $\exists s \in T \cdot \exists \cdot \{E_u(s) \neq \emptyset; \text{meas}[E_u(s)] = 0\}$ (KN1)

or $\forall t \in T \{E_u(t) \neq \emptyset; \text{meas}[\bigcap_t E_u(t)] = 0\}$ (KN2)

or $\exists E_u$ indep. of $t \cdot \exists \cdot \{E_u \neq \emptyset; \text{meas}[E_u] = 0\}$ (KN2.1)

or $\forall t \in T, \{E_u(t) \neq \emptyset; \text{meas}[E_u(t)] = 0\}$ (KN2.2)

THEN $\tilde{a} =_{a.e.} \hat{a}$.

(*) *SICON*, (1977) 15, 785-802

STABILITY ESTIMATE

in L^∞ (Cauchy-unique solution)

Hp 1) (reference and second potentials)

$$u, v \in \mathcal{X} := \mathcal{C}^0(\bar{T}, H^2(D)) \cap \mathcal{C}^1(\bar{T}, L^2(D))$$

2) (available data)

$$u, u_t, v, v_t \text{ @ } t = \tau$$

$$3) \left| \frac{1}{v_x} \right|(\tau) \leq c_v ; \quad \|v_{xx}\|_{0,2}(\tau) \leq c_2$$

4) (reference solution)

$$\hat{a}(u, t) \in \mathcal{C}^1(\bar{D} \setminus \{y_i\}) ; y_i \neq x_0, x_1, t_i$$

$$\text{Rem. 1) } \hat{a}_x = \sum_i c_i \delta(x - y_i) + \sum_i \psi_{i,x} \chi(y_i, y_{i+1})$$

$$\text{Hp. 5) } \sum_i |c_i| < \infty \quad \text{Biblioteca} \Rightarrow \{ |a_x|^{[-1]} \} \subset L^\infty(D)$$

$$6) \exists b(v, t) \in \text{Ad} ; b - \hat{a} := g \in \text{Bad}$$

Rem. 2) (defect ee.) **Zuadrelli**

$$\{ R^{[-1]} \}(\tau) \in L^\infty(D) ; \exists \lim_{x \rightarrow x_0^+} R^{[-1]}(\tau)$$

$$\text{Th. } \|b - \hat{a}\|_{0,\infty} \leq [1 + \|\hat{a}\|_{0,\infty} + \| |\hat{a}_x|^{[-1]} \|_{0,\infty}] \cdot c_v.$$

$$\cdot \|v - u\|_{\mathcal{X}(\tau)} \cdot \exp [c_v c_2 \sqrt{\text{meas}[D]}]$$

$$\|w\|_{\mathcal{X}(\tau)} := \max_{\bar{D}} (|w| + |w_x|)(\tau) + \sqrt{\text{meas}[D]} [\|w_t\|_{0,2} + \|w_{xx}\|_{0,2}](\tau)$$

STABILITY ESTIMATE

L^1 (KN2 - unique solution)

Hp. 1) $u \in \mathcal{X}$ (as above)

2) (special case) $E_u(t) = [\xi_u(t), \bar{\xi}_u(t)]$

Def. 1) $I_u(t) := [x_0, \xi_u(t)]$; $J_u := (\bar{\xi}_u(t), x_1]$

Rem. 1) $\bar{D} \setminus E_u(t) = I_u(t) \cup J_u(t)$

Hp. 3) $\frac{1}{u_x} \in \mathcal{C}^0(\bar{T}, L^1(D \setminus E_u(t)))$ i.e. $(\frac{1}{u_x})(t) \in L^1(D \setminus E_u(t)), \forall t$

Def. 2) $I_a := [\min_{\bar{T}} \xi_u(t) - \varepsilon, \max_{\bar{T}} \bar{\xi}_u(t) + \varepsilon] \cap \bar{D}$; $\varepsilon > 0$

Hp. 4) $\hat{a} \in \mathcal{C}^0(I_a) \cap A_{ad}$ *Biblioteca*

5) $v \in \mathcal{X}$, $E_v(t) \neq \emptyset$, $\bigcup_{\bar{T}} E_v(t) \subseteq I_a$
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6) $\text{meas}[\bigcap_{\bar{T}} E_v(t)] = 0$ $\text{meas}[\bigcap_{\bar{T}} E_v(t)] > 0$

7) $(\frac{1}{v_x})(t) \in L^1(D \setminus E_v(t))$, $\forall t \in \bar{T}$ *Crosta*

8) $\max_{\bar{T}} \|\frac{1}{v_x}\|_{L^1(D \setminus E_v(t))} \leq c_v$

Notation $\mathcal{Y} := L^1(D \setminus \bigcap_{\bar{T}} E_v(t))$

Th. $\|b - \hat{a}\|_{L^1(D)} \leq \|b - \hat{a}\|_{\mathcal{Y}} \leq 2c_v(1 + 2\|\hat{a}\|_{0,\infty})\|v - u\|_{\mathcal{X}}$