

$$\Gamma \equiv \partial\Omega$$

$$\underline{\mathbf{b}}^{(L)} \equiv \vec{\beta}^{(L)}$$

THE $X_1^{(L)}$ ALS SCHEME AND SUCCESSIVE APPROXIMATIONS

DEF: $\Omega \in \text{RAYLEIGH Obstacle Uniform Normal Derivative}$ class if $\sum_{\lambda} f_{\lambda} \partial_N v_{\lambda}[\mathbf{x}]$ converges uniformly to $\partial_N E_z^{(sc)}|_{\Gamma}$, $\forall \mathbf{x} \in \Gamma$.

THM J2.3 (successive approximations in the infinite dimensional case).
Let $\Omega \in \text{ROUND}$. Assume $\mathbf{f} \in \ell_2$ and $RL: \ell_2 \rightarrow \ell_2$ is bounded. If $r_{\sigma}[RL] < 1$, then, $\forall \mathbf{b} \in \ell_2$, there exists a unique solution, \mathbf{f} , to

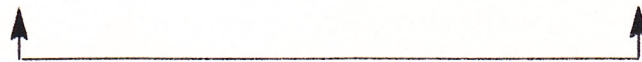
$$\mathbf{f} = \mathbf{b} + RL \cdot \mathbf{f},$$

obtained by successive approximations, where t is the iteration index i.e.,

$$\mathbf{p}^{[t+1]} = \mathbf{b} + RL \cdot \mathbf{p}^{[t]}, t = 0, 1, 2, \dots$$

started with an arbitrary $\mathbf{p}^{[0]} \in \ell_2$.

Proof: $\Omega \in \text{ROUND} \Rightarrow f_{\lambda} = -\frac{i}{4} \langle u_{\lambda}|_{\Gamma} \partial_N E_z^{(inc)} + \sum_{\mu} f_{\mu} \partial_N v_{\mu} \rangle$; then



recall the contraction mapping THEOREM.

THM J2.4 (infinite vs. finite dimensional propagators)

Let $\Omega \in \text{ROUND}$, \mathbf{f} , \mathbf{b} and RL as in THM J2.3. Assume

$$r_{\sigma}[RL^{(L)}] < 1, \forall L \text{ and } r_{\sigma}[RL] < 1$$

then the following hold

- I) $\forall L \exists!$ fixed point $\bar{\mathbf{c}}^{(L)}$ such that

$$\bar{\mathbf{c}}^{(L)} = \mathbf{b}^{(L)} + RL^{(L)} \cdot \bar{\mathbf{c}}^{(L)} \text{ i.e., } \bar{\mathbf{c}}^{(L)} = [\mathbf{1}^{(L)} - RL^{(L)}]^{-1} \cdot \mathbf{b}^{(L)}$$
- II) $\lim_{L \rightarrow \infty} \bar{\mathbf{c}}^{(L)} = \mathbf{f}$.
- III) $\lim_{L \rightarrow \infty} \mathbf{p}^{(L)} = \mathbf{f}$.

Proof: Since $\mathbf{b}^{(L)} \rightarrow \mathbf{b}$, $\mathbf{1}^{(L)} - RL^{(L)} \rightarrow \mathbf{1} - RL$ and $[\mathbf{1}^{(L)} - RL^{(L)}]^{-1} \rightarrow [\mathbf{1} - RL]^{-1}$ then $\bar{\mathbf{c}}^{(L)} \rightarrow \mathbf{f}$ (convergence of the projection method).

THE NUMERICAL DETERMINATION OF SPECTRAL RADII

Scope: find a non trivial, non empty set such that, THM J2.3 holds.

PROP J2.5 [DÉMIDOVITCH & MARON, 1979, Ch. XII, § 11]

$$r_{\sigma}[RL^{(L)}] \approx r_{\sigma}^{(M)}[RL^{(L)}] := \left| \frac{\text{Tr}[RL^{(L)}]^{M+1}}{\text{Tr}[RL^{(L)}]^M} \right|, M \text{ large.}$$

(Stop @ M such that, $|r_{\sigma}^{(M+1)} - r_{\sigma}^{(M)}| < 10^{-7}$).

REMARKS

◆ If Γ is a disk, then $r_{\sigma}[RL^{(L)}] = \max_{0 \leq l \leq L} |RL^{(L)}_{plpl}|$, where

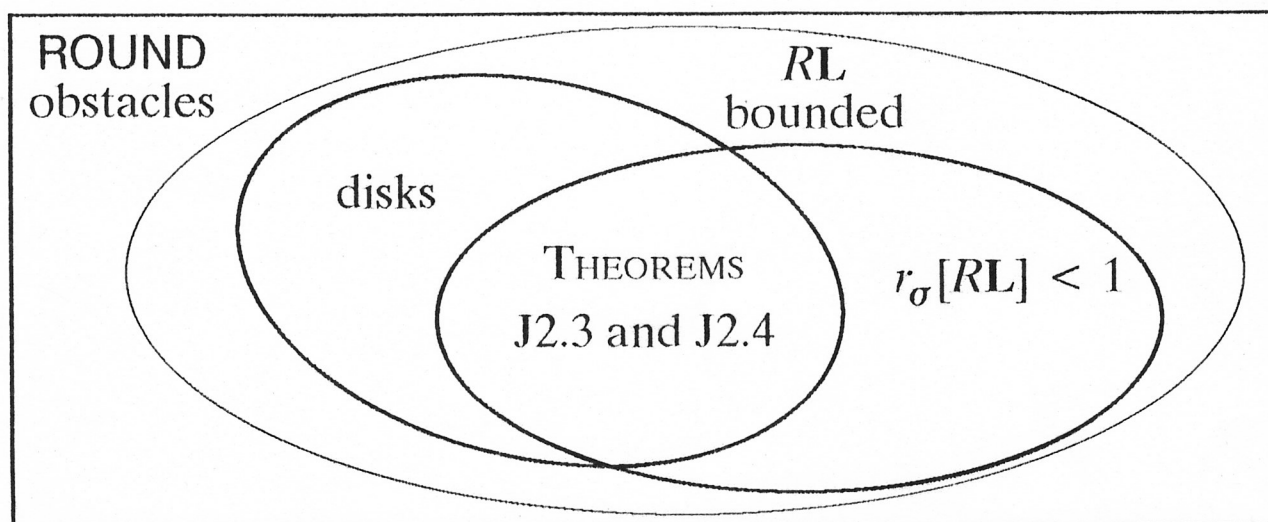
$$RL^{(L)}_{plpl} = -\frac{i}{2} \pi k R J_l[kR] \frac{d}{dz} H_l^{(1)}[kR], p = 0, 1.$$

◆ $r_{\sigma}[RL^{(L)}]$ depends on $\{L, k, \vec{\psi}\}$, **not** on $\hat{\mathbf{k}}$.

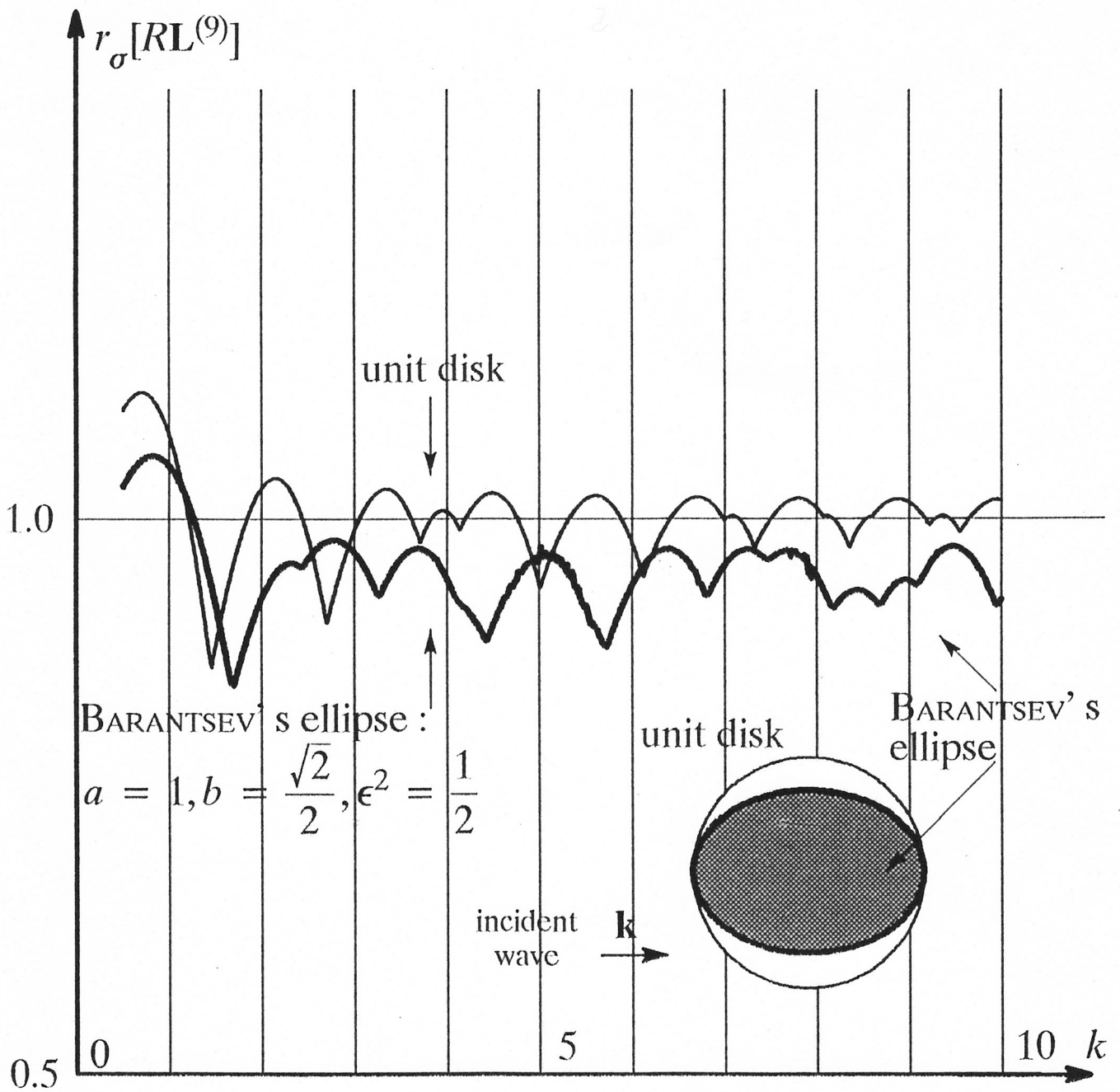
◆ When $\Gamma = S_R^{n-1}$, there is no contradiction between the consistency property (THM J2.1) and the result $r_{\sigma}[RL^{(L)}] > 1$ for some $\{L, kR\}$. Namely, consistency is verified directly and does not involve any iterative scheme.

♠ THMS J2.3 and J2.4 only provide a sufficient condition for the convergence of forward propagation.

The relationships known to date among the conditions on RL .



COMPUTED SPECTRAL RADII



Unit disk: direct calculation.

BARANTSEV's ellipse: by PROP J2.5.

$10 < M[k] < 2000$, strongly affected by k .

THE TRUSTED METHOD INEQUALITY

Recall: $\mathbf{c}^{(L)}$ = initial value ; $\mathbf{p}^{(L)}$ = first iterate.

COR J2.6 (to THM J2.4)

Fix L , then $\|\mathbf{c}^{(L)} - \bar{\mathbf{c}}^{(L)}\| < \|\mathbf{p}^{(L)} - \bar{\mathbf{c}}^{(L)}\|$. (Norms in $\mathbb{C}^{\text{card}[\Lambda(L)]}$).

DEF A method is trusted with respect to \mathbf{f} if it returns $\bar{\mathbf{c}}^{(L)}$ such that, given $\epsilon > 0$,

$$|f_\lambda - \bar{c}_\lambda^{(L)}| < \epsilon |\bar{c}_\lambda^{(L)}|, \forall \lambda \in \Lambda(L).$$

PROP J2.7 (a sufficient condition for the effectiveness of forward propagation)

If $\exists \epsilon > 0$, small such that, $\forall \lambda \in \Lambda(L)$

a) $|f_\lambda - \bar{c}_\lambda^{(L)}| < \epsilon |\bar{c}_\lambda^{(L)}|$ and

b) $|p_\lambda^{(L)} - \bar{c}_\lambda^{(L)}| + 2\epsilon |\bar{c}_\lambda^{(L)}| < |c_\lambda^{(L)} - \bar{c}_\lambda^{(L)}|$

then ALS forward propagation is effective i.e.,

$$|p_\lambda^{(L)} - f_\lambda| < |c_\lambda^{(L)} - f_\lambda|.$$

REMARKS

♠ COR J2.6 $\not\Rightarrow |c_\lambda^{(L)} - \bar{c}_\lambda^{(L)}| < |p_\lambda^{(L)} - \bar{c}_\lambda^{(L)}|$, $\lambda \in \Lambda(L)$.

♠ The effectiveness of ALS remains an open problem.

PROP J2.8 (How small shall ϵ be for a method to be trusted ?)

If \mathbf{f} unknown, then a method, which returns $\bar{\mathbf{c}}^{(L)}$, is a candidate for trust provided it is ϵ -accurate, where

$$\epsilon < \max_{\lambda \in \Lambda(L)} \frac{|\bar{c}_\lambda^{(L)} - c_\lambda^{(L)}| - |\bar{c}_\lambda^{(L)} - p_\lambda^{(L)}|}{2|\bar{c}_\lambda^{(L)}|}.$$

MORE QUESTIONS AND OPEN PROBLEMS

- Q1 How many IPSWICH data sets are needed to imply the uniqueness (if any) of the unknown shape ?
- Q2 (approximation) In view of THM J1.2, are cylindrical wave functions the appropriate basis ?
- Q3 (approximation) What is the role of approximation and parameterization orders, $\{ I, L \}$, in uniqueness and stability ?
- Q4 Is $\vec{\gamma}$ the proper unknown to represent phase corrections of the IPSWICH data ?
- Q5 Are conjugate directions the best descent rule ?
- Q6 How will other backpropagation methods e.g., the $W^{(L)}$ method [1994, 1995] perform ?
- Q7 How will penalty methods (ANGELL-KLEINMAN-ROACH [1987], RAMM [1994]) compare ?