

Aug 31

M. Chairman, ladies & gentlemen (Y. Stirozhew)
 I will provide some stability results pertaining to ~~identifi-~~^{a @ suprinto uo a p}
~~fication for control~~, with ~~specific reference to a model of~~^{arising from a problem}
 environmental interest.

(P3) The physical process I refer to is steady flow across
 a one-dimensional medium (non homogeneous).

In the open interval (x_0, x_1) the potential u , conduc-
 tivity a and the source term f are related by this ODE.

Nomenclature: a direct problem consists of determi-
 ning u inside the interval, given a, f and boundary
 values of u .

An inverse problem is met when a has to be found
 from f, u and supplementary information.

(L1) Let me raise the following question:

is the determination of conductivity really the ulti-
 mate goal, given the application we have in mind?

The answer is no, as stressed by the following state-
 ment by prof. E. Seidman

Let us look at this diagram, which summarizes
 information flow:

~~The identification of coefficients appearing in an ordinary
 or partial DE is just a part of a procedure: the iden-
 tified coefficients, together with a new pair of bounda-
 ry values and a new source term give rise to a
 direct (a control) problem, the purpose of which is
 to determine a new result, ~~the~~~~

First of all, from $\{u, f\}$ and extra information,
 the distributed parameter a has to be determined uni-
 quely - this involves the data-to-parameter map.

Next, the parameter a together with a new source
 term f_0 and new BV is used to determine the new
 potential v ; this involves the parameter-to-result
 map.

What I am interested in is the well-posedness of the overall map

(L2) And this is the plan

I will provide some conditions under which \underline{a} is uniquely determined from the available pieces of information

Since the original flow equation is in fact a 1st order linear ODE wr to \underline{a} , if existence of a solution is given, then the uniqueness of \underline{a} can be provided by a Cauchy datum.

Cauchy problems can be either regular or singular. This remark provides a unifying view not only over identifiability conditions but also over stability estimates, as we shall see.

About the control map, uniqueness is trivial and well-posedness are therefore I am after the stability of the composite map.

(P4) Before going into details, let me examine the general context.

Enduevity characterizes the physical system out of which first we get both the data (map \underline{P}) and the results (map \underline{Q}). Since we have to go from the data to the results, we have to consider the composite map $\underline{Q} \circ \underline{P}^{-1}$. Hence we want \underline{P}^{-1} to behave in the best possible way. Among the required properties is continuity of \underline{P}^{-1} (often referred to as stability).

This theorem provides a sufficient condition for the continuity of \underline{P}^{-1} .

The typical situation is depicted by this abstract example, based on Seddman's paper.

Usually the parameter set A is not compact.

however there \exists a compact imbedding \underline{E} of the normed space X into A ○

Define B_M the sphere of radius M in X . Assume the inverse problem consists of finding \bar{a} in $X \rightarrow \bar{a}$. This operator equation is ~~not~~ solved

Define A_* as the closure of the image of B_M according to \underline{E} . ○

Assume that prior knowledge leads to seeking for solutions in A_* i.e. that the restriction P_* of P to A_* needs to be considered. ○

Under these circumstances the Theorem applies i.e., P_*^{-1} is continuous (stable).

⑬ So far for a sufficient stability condition holding for the most general situation

Let me go back to the specific problem. I will go through some details and eventually compare the final stability result with the make a comparison between the two procedures; the specific and the general one.

One way of achieving uniqueness for the data-to-parameter map is by providing two suitable data pairs.

Everything here is set in classical function spaces. In fact, it could not be otherwise, if this is to make any sense at all.

The two potentials are of class C^1 . Let E_u, E_v denote the sets of critical points of u , resp. v .

Let the source terms be in L^1 and let at least one of them not vanish identically, which vanish at the left endpoint

Antiderivatives of f, g are denoted by capitals

The set of admissible parameters consists of continuous functions, which are bounded away from zero.

Let there \exists at least one admissible conductivity s.t., the two following flow equations hold simultaneously.

Let the potentials be nowhere stationary.

Finally let the following independence condition hold.:

Here \exists a pair of points y_1, y_2 in D , \Rightarrow this distance does not vanish the pilot points

then conductivity is uniquely and is represented by this quotient, where the constant C_1 is explicitly shown here as a function of u', v', F, G .

u' , stands for the value of u' at y_1 & so on

(L4) Now assume u is stationary at just one point, x_u . then conductivity can be uniquely identified from the $\{$ potential, source term $\}$ pair and is given by this quotient.

This Cauchy problem is singular, because it relies on information supplied at the point x_u , where the coefficient u' of a' vanishes.

This is the simplest example of the uniqueness conditions $K+N$ stated in 1977

(L5) Let me come to stability for the composite map. to begin with, I assume uniqueness is due to independence.

Information flow is summarized here.

The two top data pairs, where v is named the reference potential, yield a ; this a enters the direct problem when combined with these BVs and this source term the result is v , the reference result.

If I replace v by say a "noisy" replica w , & if the independence condition continues to hold at the same pilot points, and leave everything else unchanged. in the bottom data pair, then I get another conductivity, b . the corresponding potential is s , the "noisy" result.

The purpose of a stability estimate is to find suitable Banach spaces, V and $Z \Rightarrow$ an inequality of this

type is established. The quantity \mathcal{C}_\pm here is independent of v, w and may depend on the cited quantities.

(26) It shall be pointed out that the most general stability estimate may have a more complicated form in order to achieve this goal, additional hypotheses are requested - Essentially, I need a-priori bounds -

- for L^1 norms of f & g

- for the abs values of derivatives of u & v evaluated at the pilot points

This abs value shall be bounded away from zero; this makes sense - in fact, it distinguishes regular Cauchy problems from singular ones.

Moreover these determinants shall comply with this bound and finally, the reference conductivity shall be bounded above - Note that no such inequality is needed for the second conductivity b ; if this were the case, every estimate would become almost trivial!

this is the result; a uniform $W^{1,\infty}$ estimate is established for $s-r$. The "data" space is just a set of number pairs.

The difference between derivs abits is estimated as follows. I did not choose a more synthetic way to write the inequality, because ~~the habit track has been kept for all constants appearing in the hypotheses~~ | I wanted to keep track of all constants defined in the hypotheses.

Similarly, the $W^{1,\infty}$ estimate for $s-r$ follows in a straight forward way, because the L^∞ norm of $s'-r'$ is equivalent to the $W^{1,\infty}$ norm, at least in connection with the direct to point BV problem.

(27) A similar, though simpler scheme applies to the data to results map when uniqueness comes from a singular Cauchy problem - Only 2 data pairs are needed.

(28) The regularizing hypothesis, which makes the difference from the regular Cauchy case is this:

since u' and v' shall vanish somewhere, the only bound I can apply is of integral type - for simplicity I choose to

of the reciprocals
 embed the L^1 norm μ . In fact I could do the same by selecting
 an L^p norm, where p is finite

As a consequence, the involved Banach spaces are $U = W^{1,1}$
 and $V = W^{1,\infty}$.

Assume u' and v' vanish at one and the same point,
 then the L^1 norm of $s' - r'$ is estimated as shown here.

An inequality for the $W^{1,1}$ norm of $s - r$ is obtained by
 recalling the already mentioned equivalence property be-
 tween norms.

(L9) The stability estimates obtained so far summarize as
 follows.

- when the uniqueness of \underline{a} is due to a regular Cauchy pro-
 blem, then estimates for the ~~component~~ map are of uniform
 type $(\text{data-to-parameter } \underline{P}^{-1})$

- when ~~the~~ uniqueness comes from a singular Cauchy pro-
 blem, estimates are of integral type, L^1 or L^p , with
 p ranging from greater than 1 but and finite.

Since the ~~component~~ map parameter to result (\underline{Q})
map is well posed, the component map inherits the sta-
 bility properties of \underline{P}^{-1} .

(P5) Let me go back to the general framework - I may now won-
 der whether there has been any gain in going through all of
 the above details instead of just applying a general compact-
 ness argument

If I had stuck to the general scheme, then I ought to have
 looked for a compact subset of the admissible parameter set.

- By e.g. requiring \mathcal{A} to be continuous and uniformly
 bounded

- u to be twice differentiable and bounded as shown
 here, then

the compactness of this set would have been obtained
 by applying Arzelà's theorem.

The hypotheses I have just listed shall be compared to those which I have actually used.

There has been a substantial gain, which is emphasized by this synopsis.

In other words, a proof based on the explicit representation of the solutions has been worthwhile.

To conclude, let me warmly thank IASA, the meeting organizers in particular for inviting me, and - this Italian research project for providing partial support.

Thank You for Your attention.

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