



Unique solutions to hyperbolic conservation laws with a strictly convex entropy

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Abstract

Consider a strictly hyperbolic $n \times n$ system of conservation laws, where each characteristic field is either genuinely nonlinear or linearly degenerate. In this standard setting, it is well known that there exists a Lipschitz semigroup of weak solutions, defined on a domain of functions with small total variation. If the system admits a strictly convex entropy, we give a short proof that every entropy weak solution taking values within the domain of the semigroup coincides with a semigroup trajectory. The result shows that the assumptions of “Tame Variation” or “Tame Oscillation”, previously used to achieve uniqueness, can be removed in the presence of a strictly convex entropy.

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1. Introduction

We consider the Cauchy problem for a strictly hyperbolic $n \times n$ system of conservation laws in one space dimension:

$$u_t + f(u)_x = 0, \tag{1.1}$$

$$u(0, x) = \bar{u}(x). \tag{1.2}$$

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As usual, $f : \Omega \rightarrow \mathbb{R}^n$ is the flux, defined on some open set $\Omega \subset \mathbb{R}^n$. We assume that each characteristic family is either genuinely nonlinear or linearly degenerate. In this setting, it is well known [8,10,11,16,20,23] that there exists a Lipschitz continuous semigroup $S : \mathcal{D} \times [0, +\infty[\mapsto \mathcal{D}$ of entropy weak solutions [8, Section 7.7], defined on a domain

$$\mathcal{D} = cl \left\{ u \in \mathbf{L}^1(\mathbb{R}; \mathbb{R}^n); u \text{ is piecewise constant and } \mathbf{V}(u) + C_0 \mathbf{Q}(u) < \delta_0 \right\} \tag{1.3}$$

containing all functions with sufficiently small total variation. Here $\mathbf{V}(u)$ and $\mathbf{Q}(u)$ are respectively the *total strength of waves* and the *interaction potential* of u defined in [8, (7.99)] and C_0, δ_0 are two suitable positive constants. The trajectories of this semigroup are the unique limits of front tracking approximations, and also of Glimm approximations [7] and of vanishing viscosity approximations [6]. We recall that the semigroup is globally Lipschitz continuous w.r.t. the \mathbf{L}^1 distance. Namely, there exists a constant L such that

$$\|S_t \bar{u} - S_s \bar{v}\|_{\mathbf{L}^1} \leq L \left(|t - s| + \|\bar{u} - \bar{v}\|_{\mathbf{L}^1} \right) \quad \text{for all } s, t \geq 0, \bar{u}, \bar{v} \in \mathcal{D}. \tag{1.4}$$

Given any weak solution $u = u(t, x)$ of (1.1)-(1.2), various conditions have been derived in [12,14,15] which guarantee the identity

$$u(t) = S_t \bar{u} \quad \text{for all } t \geq 0. \tag{1.5}$$

Since the semigroup S is unique, the identity (1.5) yields the uniqueness of solutions to the Cauchy problem (1.1)-(1.2). In addition to the standard assumptions, earlier results required some additional regularity conditions, such as ‘‘Tame Variation’’ or ‘‘Tame Oscillation’’, controlling the behavior of the solution near a point where the variation is locally small.

Aim of the present note is to show that, if the $n \times n$ system (1.1) is endowed with a strictly convex entropy $\eta(\cdot)$, then every entropy-weak solution $t \mapsto u(t)$ taking values within the domain \mathcal{D} of the semigroup satisfies (1.5). In other words, uniqueness is guaranteed without any further regularity assumption.

As in [12,14,15], the proof relies on the elementary error estimate

$$\|u(t) - S_t \bar{u}\|_{\mathbf{L}^1} \leq L \cdot \int_0^t \liminf_{h \rightarrow 0^+} \frac{\|u(\tau + h) - S_h u(\tau)\|_{\mathbf{L}^1}}{h} d\tau. \tag{1.6}$$

Assuming that the system is endowed with a strictly convex entropy, we will prove that the integrand is zero for a.e. time $\tau \geq 0$. Following an argument introduced in [7], this is achieved by two estimates:

- (i) In a neighborhood of a point (τ, y) where $u(\tau, \cdot)$ has a large jump, the weak solution u is compared with the solution to a Riemann problem.
- (ii) In a region where the total variation is small, the weak solution u is compared with the solution to a linear system with constant coefficients.

The main difference is that here we estimate the lim-inf in (1.6) only at times τ which are Lebesgue points for a countable family of total variation functions $W^{\xi, \zeta}(\cdot)$, defined at (3.5).

To precisely state the result, we begin by collecting the main assumptions.

(A1) (Conservation equations) *The function $u = u(t, x)$ is a weak solution of the Cauchy problem (1.1)-(1.2) taking values within the domain of the semigroup. More precisely, $u : [0, T] \mapsto \mathcal{D}$ is continuous w.r.t. the \mathbf{L}^1 distance. The identity $u(0, \cdot) = \bar{u}$ holds in \mathbf{L}^1 , and moreover*

$$\iint (u\varphi_t + f(u)\varphi_x) \, dxdt = 0 \tag{1.7}$$

for every \mathcal{C}^1 function φ with compact support contained inside the open strip $]0, T[\times \mathbb{R}$.

Regarding the entropy conditions, we assume that the system (1.1) admits a \mathcal{C}^2 entropy function $\eta : \Omega \mapsto \mathbb{R}$ with entropy flux q , so that the equality $\nabla q(\omega) = \nabla \eta(\omega) Df(\omega)$ holds for all $\omega \in \Omega$. We also assume that the entropy η satisfies the strict convexity condition

$$\eta(\omega) \geq \eta(\bar{\omega}) + \nabla \eta(\bar{\omega}) \cdot (\omega - \bar{\omega}) + c_0 |\omega - \bar{\omega}|^2, \tag{1.8}$$

for some $c_0 > 0$ and every couple of states $\omega, \bar{\omega} \in \Omega$. As usual, we say that a weak solution u is entropy-admissible if it satisfies:

(A2) (Entropy admissibility condition) *For every \mathcal{C}^1 function $\varphi \geq 0$ with compact support contained inside the open strip $]0, T[\times \mathbb{R}$, one has*

$$\iint (\eta(u)\varphi_t + q(u)\varphi_x) \, dxdt \geq 0. \tag{1.9}$$

Our result can be simply stated as:

Theorem 1.1. *Let (1.1) be a strictly hyperbolic $n \times n$ system, where each characteristic field is either genuinely nonlinear or linearly degenerate, and which admits a strictly convex entropy $\eta(\cdot)$ as in (1.8). Then every entropy-weak solution $u : [0, T] \mapsto \mathcal{D}$, taking values within the domain of the semigroup, coincides with a semigroup trajectory.*

The theorem will be proved in Section 3. We remark that, restricted to a class of 2×2 systems, a more elaborate proof of this result was recently given in [19].

In our view, the main interest in the above uniqueness theorem is that, combined with a compactness argument, it yields a uniform convergence rate for a very wide class of approximation algorithms. This will be better explained in the concluding remarks contained in Section 4.

2. Preliminary lemmas

Let M be an upper bound on the total variation of all functions in the domain \mathcal{D} of the semigroup:

$$\text{Tot.Var. } \{u; \mathbb{R}\} \leq M, \quad \text{for all } u \in \mathcal{D}. \tag{2.1}$$

Since by assumption our solution $u(t, \cdot) \in \mathcal{D}$, for sake of definiteness we shall assume that it is right continuous, namely $u(t, x) = \lim_{y \rightarrow x^+} u(t, y)$. By [20, Theorem 4.3.1], we have the Lipschitz bound

$$\|u(t_2, \cdot) - u(t_1, \cdot)\|_{L^1(\mathbb{R})} \leq C_M (t_2 - t_1) \quad \text{for all } 0 \leq t_1 \leq t_2, \tag{2.2}$$

for some constant $C_M > 0$ depending only on M and on the flux f .

We begin by reviewing the well known fact that the entropy has finite propagation speed. The proof relies on the notion of relative entropy, see [24] for an overview of the subject.

Lemma 2.1. *Let $u = u(t, x)$ be a function satisfying (A1) and (A2). Then there exists two constants $\widehat{C}, \widehat{\lambda} > 0$ such that the following holds. For any constant state $u^* \in \Omega$, any $a < b$, and any $0 \leq \tau < \tau'$ with $2\widehat{\lambda}(\tau' - \tau) < b - a$, one has*

$$\int_{a+\widehat{\lambda}(\tau'-\tau)}^{b-\widehat{\lambda}(\tau'-\tau)} |u(\tau', x) - u^*|^2 dx \leq \widehat{C} \int_a^b |u(\tau, x) - u^*|^2 dx. \tag{2.3}$$

Proof. Given the constant state $u^* \in \Omega$, for all $\omega \in \Omega$ define the relative entropy $\eta(\omega | u^*)$ and the corresponding entropy flux $q(\omega | u^*)$ as

$$\begin{aligned} \eta(\omega | u^*) &= \eta(\omega) - \eta(u^*) - \nabla \eta(u^*)(\omega - u^*), \\ q(\omega | u^*) &= q(\omega) - q(u^*) - \nabla \eta(u^*)(f(\omega) - f(u^*)). \end{aligned} \tag{2.4}$$

The equations (1.7) and (1.9) yield

$$\eta(u | u^*)_t + q(u | u^*)_x \leq 0, \tag{2.5}$$

while (1.8) implies

$$\eta(\omega | u^*) \geq c_0 |\omega - u^*|^2, \quad \text{for all } \omega, u^* \in \Omega. \tag{2.6}$$

By the C^2 regularity of the functions η, q , there exists a constant C' such that

$$\eta(\omega | u^*) \leq C' |\omega - u^*|^2, \quad |q(\omega | u^*)| \leq C' |\omega - u^*|^2, \quad \text{for all } \omega, u^* \in \Omega. \tag{2.7}$$

In view of (2.6), there exists a sufficiently large constant $\widehat{\lambda} > 0$ such that

$$-\widehat{\lambda} \eta(\omega | u^*) \pm q(\omega | u^*) \leq 0, \quad \text{for all } \omega, u^* \in \Omega. \tag{2.8}$$

Using (2.5), in connection with test functions that approximate the characteristic function of the trapezoid

$$\Gamma = \{(t, x); \tau < t < \tau', \ a + \widehat{\lambda}(t - \tau) < x < b - \widehat{\lambda}(t - \tau)\},$$

and recalling (2.8), we obtain

$$\begin{aligned}
 \int_{a+\hat{\lambda}(\tau'-\tau)}^{b-\hat{\lambda}(\tau'-\tau)} \eta(u | u^*)(\tau', x) dx &\leq \int_a^b \eta(u | u^*)(\tau, x) dx \\
 &+ \int_{\tau}^{\tau'} \left(-\hat{\lambda} \eta(u | u^*) + q(u | u^*) \right) \left(t, a + \hat{\lambda}(t - \tau) \right) dt \\
 &+ \int_{\tau}^{\tau'} \left(-\hat{\lambda} \eta(u | u^*) - q(u | u^*) \right) \left(t, b - \hat{\lambda}(t - \tau) \right) dt \\
 &\leq \int_a^b \eta(u | u^*)(\tau, x) dx.
 \end{aligned}$$

Together with (2.6)-(2.7), this proves the lemma. \square

Throughout the following, without loss of generality we shall always assume $\hat{\lambda} = 1$. We observe that this can always be achieved by a suitable rescaling of the time variable:

$$\tilde{t} = \kappa t.$$

Similarly, to simplify notation, we also assume that all wave speeds lie in the interval $[-1, 1]$.

Given any $\tau \geq 0$ and any bounded interval $]a, b[$ with $-\infty \leq a < b \leq +\infty$, we consider the open intervals

$$J(t) =]a + (t - \tau), b - (t - \tau)[, \quad \tau \leq t < \tau + \frac{b - a}{2}. \tag{2.9}$$

Toward the proof of Theorem 1.1, in order to replace the ‘‘Tame Variation’’ condition, the main tool is provided by the following elementary lemma.

Lemma 2.2. *In the setting of Theorem 1.1, for some constant $C > 0$ the following holds. Let $u = u(t, x)$ be any entropy weak solution to (1.1). Then*

$$\int_{J(t)} |u(t, x) - u(\tau, x)| dx \leq C(t - \tau) \cdot \text{Tot.Var.}\{u(\tau, \cdot);]a, b[\}. \tag{2.10}$$

Proof. 1. We first consider the case where $-\infty < a < b < +\infty$. For notational simplicity, w.l.o.g. we assume that $\tau = 0$. Given a time $0 < t < \frac{b-a}{2}$, as shown in Fig. 1 we define the points x_k , the values u_k and the integer $N \geq 1$ such that

$$x_k = a + kt, \quad u_k = u(0, x_k), \quad x_N \leq b < x_{N+1}. \tag{2.11}$$

For $k = 1, 2, \dots, N - 2$, we apply Lemma 2.1 with $u^* = u_k$ on the trapezoids

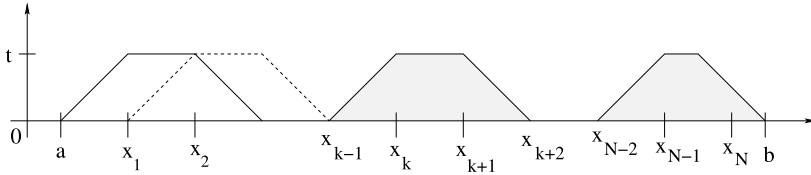


Fig. 1. The covering of the interval $[a, b]$ used in the proof of Lemma 2.2.

$$\Gamma_k \doteq \{(s, x); s \in [0, t], x_{k-1} + s < x < x_{k+2} - s\}.$$

Then we apply the same lemma with $u^* = u_{N-1}$ on the domain

$$\tilde{\Gamma}_N \doteq \{(s, x); s \in [0, t], x_{N-2} + t < x < b - t\}.$$

This yields the estimates

$$\begin{aligned} \int_{x_k}^{x_{k+1}} |u(t, x) - u_k|^2 dx &\leq \widehat{C} \int_{x_{k-1}}^{x_{k+2}} |u(0, x) - u_k|^2 dx \\ &\leq \widehat{C} \cdot 3t \cdot \left(\text{Tot.Var.}\{u(0, \cdot);]x_{k-1}, x_{k+2}[\} \right)^2, \end{aligned} \tag{2.12}$$

$$\int_{x_{N-1}}^{b-t} |u(t, x) - u_{N-1}|^2 dx \leq \widehat{C} \cdot 3t \cdot \left(\text{Tot.Var.}\{u(0, \cdot);]x_{N-2}, b[\} \right)^2. \tag{2.13}$$

2. Define the piecewise constant approximation $\bar{u} : [a + t, b - t] \mapsto \Omega$ by setting

$$\bar{u}(x) = u_k \quad \text{if } x \in [x_k, x_{k+1}[, \quad k = 1, \dots, N - 1. \tag{2.14}$$

Using Cauchy’s inequality and the bounds (2.12)-(2.13), we obtain

$$\begin{aligned} \int_{a+t}^{b-t} |u(t, x) - \bar{u}(x)| dx &= \sum_{k=1}^{N-2} \int_{x_k}^{x_{k+1}} |u(t, x) - u_k| dx + \int_{x_{N-1}}^{b-t} |u(t, x) - u_{N-1}| dx \\ &\leq \sum_{k=1}^{N-2} \sqrt{t} \left(\int_{x_k}^{x_{k+1}} |u(t, x) - u_k|^2 dx \right)^{1/2} + \sqrt{t} \left(\int_{x_{N-1}}^{b-t} |u(t, x) - u_{N-1}|^2 dx \right)^{1/2} \\ &\leq \sqrt{t} \cdot \sqrt{\widehat{C} \cdot 3t} \cdot \left(\sum_{k=1}^{N-2} \text{Tot.Var.}\{u(0, \cdot);]x_{k-1}, x_{k+2}[\} + \text{Tot.Var.}\{u(0, \cdot);]x_{N-2}, b[\} \right). \end{aligned} \tag{2.15}$$

Observing that every point $x \in [a, b]$ is contained in at most three open intervals $]x_{k-1}, x_{k+2}[$, from (2.15) we conclude

$$\int_{a+t}^{b-t} |u(t, x) - \bar{u}(x)| dx \leq \sqrt{3\widehat{C}} \cdot 3t \cdot \text{Tot.Var.}\{u(0, \cdot);]a, b[\}. \tag{2.16}$$

3. Next, we compute

$$\begin{aligned} \int_{a+t}^{b-t} |u(0, x) - \bar{u}(x)| dx &= \sum_{k=1}^{N-2} \int_{x_k}^{x_{k+1}} |u(0, x) - u_k| dx + \int_{x_{N-1}}^{b-t} |u(0, x) - u_{N-1}| dx \\ &\leq \sum_{k=1}^{N-2} t \cdot \text{Tot.Var.}\{u(0, \cdot);]x_k, x_{k+1}[\} + t \cdot \text{Tot.Var.}\{u(0, \cdot);]x_{N-1}, b-t[\} \\ &\leq t \cdot \text{Tot.Var.}\{u(0, \cdot);]a, b[\}. \end{aligned} \tag{2.17}$$

Combining (2.16) with (2.17) we obtain a proof of the lemma for finite a and b .

Letting $a \rightarrow -\infty$ or $b \rightarrow +\infty$ we see that the same conclusion remains valid also for unbounded intervals, such as $] -\infty, b[$ or $]a, +\infty[$. \square

3. Proof of the theorem

We are now ready to give a proof of Theorem 1.1, in several steps.

1. By the structure theorem for BV functions [1,22], [8, Theorem 2.6], there is a null set of times $\mathcal{N} \subset [0, T]$ such that the following holds.

Every point $(\tau, \xi) \in [0, T] \times \mathbb{R}$ with $\tau \notin \mathcal{N}$ has the following property: there exist states $u^-, u^+ \in \mathbb{R}^n$ and a speed $\lambda \in \mathbb{R}$ such that, calling

$$U(t, x) \doteq \begin{cases} u^- & \text{if } (x - \xi) < \lambda(t - \tau), \\ u^+ & \text{if } (x - \xi) > \lambda(t - \tau), \end{cases} \tag{3.1}$$

there holds

$$\lim_{r \rightarrow 0^+} \frac{1}{r^2} \int_{-r}^r \int_{-r}^r |u(\tau + t, \xi + x) - U(\tau + t, \xi + x)| dx dt = 0. \tag{3.2}$$

When (3.1), (3.2) hold with $u^- \neq u^+$ we say that (τ, ξ) is a point of approximate jump of the function u . If instead $u^- = u^+$ we say that u is approximately continuous at the point (τ, ξ) [8, Definition 2.1]. The conservation equations (1.7) imply that the piecewise constant function U must be a weak solution to the system of conservation laws (see [8, Theorem 4.1]), satisfying the Rankine-Hugoniot equations:

$$f(u^+) - f(u^-) = \lambda(u^+ - u^-). \tag{3.3}$$

Moreover, the entropy condition (1.9) implies

$$q(u^+) - q(u^-) \leq \lambda(\eta(u^+) - \eta(u^-)). \tag{3.4}$$

Next, we observe that, for every couple of rational points $\xi, \zeta \in \mathbb{Q}$, the scalar function

$$W^{\xi, \zeta}(t) \doteq \begin{cases} \text{Tot. Var. } \{u(t);]\xi + t, \zeta - t[\} & \text{if } \xi + t < \zeta - t, \\ 0 & \text{otherwise,} \end{cases} \tag{3.5}$$

is bounded and measurable (indeed, it is lower semicontinuous). Therefore a.e. $t \in [0, T]$ is a Lebesgue point. We denote by $\mathcal{N}' \subset [0, T]$ the set of all times t which are NOT Lebesgue for at least one of the countably many functions $W^{\xi, \zeta}$. Of course, \mathcal{N}' has zero Lebesgue measure.

In view of (1.6), we will prove the theorem by establishing the following claim.

(C) For every $\tau \in [0, T] \setminus (\mathcal{N} \cup \mathcal{N}')$ and $\varepsilon > 0$, one has

$$\limsup_{h \rightarrow 0^+} \frac{1}{h} \left\| u(\tau + h) - S_h u(\tau) \right\|_{L^1} \leq \varepsilon. \tag{3.6}$$

2. Assume $\tau \notin \mathcal{N} \cup \mathcal{N}'$. Since $u(\tau, \cdot)$ has bounded variation, we define points

$$\begin{aligned} -\infty &= y_{-1} < y_0 < y_1 < \dots < y_N < y_{N+1} = +\infty, \\ y_{k+1} &= \sup \left\{ x > y_k ; \text{Tot. Var. } \{u(\tau, \cdot);]y_k, x[\} \leq \varepsilon \right\}. \end{aligned}$$

Since $u(\tau, \cdot)$ is right continuous, we have

$$\begin{cases} \text{Tot. Var. } \{u(\tau, \cdot);]y_{k-1}, y_k[\} \leq \varepsilon, & \text{for } k = 0, \dots, N + 1, \\ \text{Tot. Var. } \{u(\tau, \cdot);]y_{k-1}, y_k[\} \geq \varepsilon, & \text{for } k = 0, \dots, N, \\ N \leq \frac{M}{\varepsilon}, \end{cases} \tag{3.7}$$

where M is an upper bound for the total variation of all functions $\bar{u} \in \mathcal{D}$, as in (2.1).

Then we choose points y'_k, y''_k such that

$$\begin{cases} -\infty < y_0 < y''_0 \leq y'_1 < y_1 < y''_1 \leq y'_2 < y_2 < y''_2 < \dots \leq y'_N < y_N < +\infty \\ \text{Tot. Var. } \{u(\tau, \cdot);]y'_k, y_k[\} \leq \varepsilon^2, & k = 1, \dots, N, \\ \text{Tot. Var. } \{u(\tau, \cdot);]y_k, y''_k[\} \leq \varepsilon^2, & k = 0, \dots, N - 1, \\ \text{all values } y'_k + \tau, y''_k - \tau \text{ are rational.} \end{cases} \tag{3.8}$$

3. For any given $y \in \mathbb{R}$, we denote by $U^\sharp = U^\sharp_{(u, \tau, y)}(t, x)$ the solution, for $t \geq \tau$, to the Riemann problem for (1.1) with initial data at $t = \tau$:

$$\bar{u}(x) = \begin{cases} u(\tau, y-) & \text{if } x < y, \\ u(\tau, y+) & \text{if } x > y. \end{cases} \tag{3.9}$$

Moreover, for every given $k = 1, \dots, N$ we denote by $U^b = U^b_{(u, \tau, k)}(t, x)$ the solution to the linear Cauchy problem with constant coefficients

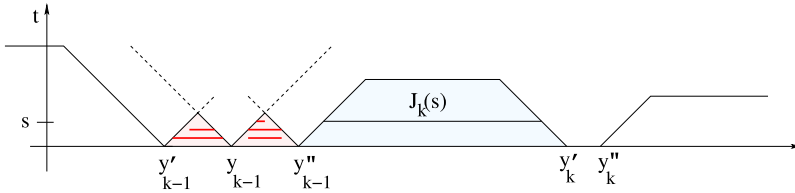


Fig. 2. The points $y'_k < y_k < y''_k$ constructed in the proof of the theorem. Typically, y_k is the location of a shock. Since $y_k \pm \tau$ need not be rational, the additional points y'_k, y''_k must be considered.

$$v_t + Av_x = 0, \quad v(\tau, x) = u(\tau, x). \tag{3.10}$$

Here the $n \times n$ matrix A is the Jacobian matrix of f computed at the midpoint of the interval $[y'_{k-1}, y'_k]$. Namely,

$$A = Df(\tilde{u}_k), \quad \tilde{u}_k = u\left(\tau, \frac{y'_{k-1} + y'_k}{2}\right), \quad k = 1, \dots, N.$$

With reference to Fig. 2, to estimate the lim-sup in (3.6), we need to estimate three types of integrals.

(I) The integral of $|u(t, x) - U_{(u;\tau,y)}^\sharp(t, x)|$ over the interval

$$[y - (t - \tau), y + (t - \tau)],$$

for all points $y \in \{y_0, y'_0, y'_1, y_1, y''_1, \dots, y'_N, y_N\}$.

(II) The integral of $|u(t, x) - U_{(u;\tau,k)}^b(t, x)|$ over the interval

$$J_k(t) =]y'_{k-1} + (t - \tau), y'_k - (t - \tau)[, \quad k = 1, \dots, N. \tag{3.11}$$

(III) The integral of $|u(t, x) - u(\tau, x)|$ over the intervals

$$\begin{cases} J'_k(t) =]y'_k + (t - \tau), y_k - (t - \tau)[, & k = 1, \dots, N, \\ J''_k(t) =]y_k + (t - \tau), y''_k - (t - \tau)[, & k = 0, \dots, N - 1, \\ J_0(t) \doteq]-\infty, y_0 - (t - \tau)[, \\ J_{N+1} \doteq]y_N + (t - \tau), +\infty[. \end{cases}$$

4. To estimate integrals of type (I), assuming that (τ, y) is either a point of approximate continuity or approximate jump of the function u , we obtain

$$\lim_{h \rightarrow 0^+} \frac{1}{h} \int_{y-h}^{y+h} |u(\tau + h, x) - U_{(u;\tau,y)}^\sharp(\tau + h, x)| dx = 0. \tag{3.12}$$

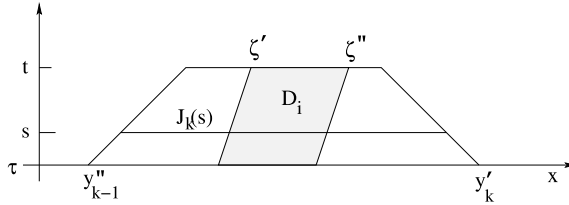


Fig. 3. The domain D_i considered at (3.15).

Indeed, by [8, Theorem 2.6], setting $u^\pm = u(\tau, y^\pm)$, the function U defined in (3.1) satisfies (3.2) and consequently u^\pm satisfy (3.3) and (3.4). It implies that $u(\tau, y^\pm)$, when different, are connected by a single entropic shock whose speed is λ . Consequently $U_{(u; \tau, y)}^\sharp$ coincides with the piecewise constant function U defined in (3.1) so that (3.12) follows from [8, Theorem 2.6].

5. We now estimate the integrals of type (II). By construction, both values $y''_{k-1} - \tau$ and $y'_k + \tau$ are rational. Hence

$$y''_{k-1} = \xi + \tau, \quad y'_k = \zeta - \tau,$$

for some $\xi, \zeta \in \mathbb{Q}$. This implies that τ is a Lebesgue point of the map

$$t \mapsto V(t) = W^{\xi, \zeta}(t). \tag{3.13}$$

Let $\tilde{\lambda}_i = \lambda_i(\tilde{u}_k)$, $\tilde{l}_i = l_i(\tilde{u}_k)$, $\tilde{r}_i = r_i(\tilde{u}_k)$, $i = 1, \dots, n$, be respectively the i -th eigenvalues and left and right eigenvectors of the matrix $A \doteq Df(\tilde{u}_k)$. We thus have

$$\tilde{l}_i \cdot U^b(t, x) = \tilde{l}_i \cdot U^b(\tau, x - (t - \tau)\tilde{\lambda}_i) = \tilde{l}_i \cdot u(\tau, x - (t - \tau)\tilde{\lambda}_i).$$

Following the proof of [8, Theorem 9.4], fix any two points $\zeta', \zeta'' \in J_k(t)$, $\zeta' < \zeta''$ and consider the quantity

$$\begin{aligned} E_i(\zeta', \zeta'') &\doteq \tilde{l}_i \cdot \int_{\zeta'}^{\zeta''} (u(t, x) - U^b(t, x)) dx \\ &= \tilde{l}_i \cdot \int_{\zeta'}^{\zeta''} (u(t, x) - u(\tau, x - (t - \tau)\tilde{\lambda}_i)) dx. \end{aligned} \tag{3.14}$$

We apply the divergence theorem to the vector $(u, f(u))$ on the domain

$$D_i \doteq \left\{ (s, x); s \in [\tau, t], \zeta' - (t - s)\tilde{\lambda}_i \leq x \leq \zeta'' - (t - s)\tilde{\lambda}_i \right\}, \tag{3.15}$$

shown in Fig. 3. Since u satisfies the conservation equation (1.1), the difference between the integral of u at the top and at the bottom of the domain D_i is thus measured by the inflow from the left side minus the outflow from the right side of D_i . From (3.14) it thus follows

$$\begin{aligned}
 E_i(\zeta', \zeta'') &= \int_{\tau}^t \tilde{l}_i \cdot \left((f(u) - \tilde{\lambda}_i u)(s), \zeta' - (t-s)\tilde{\lambda}_i \right) ds \\
 &\quad - \int_{\tau}^t \tilde{l}_i \cdot \left((f(u) - \tilde{\lambda}_i u)(s), \zeta'' - (t-s)\tilde{\lambda}_i \right) ds \\
 &= \int_{\tau}^t l_i(\tilde{u}_k) \cdot \left((f(u'(s)) - \tilde{\lambda}_i(\tilde{u}_k)u'(s)) - (f(u''(s)) - \lambda_i(\tilde{u}_k)u''(s)) \right) ds \\
 &= \int_{\tau}^t H(\tilde{u}_k, u'(s), u''(s)) ds,
 \end{aligned} \tag{3.16}$$

where we set

$$\begin{aligned}
 u'(s) &\doteq u(s, \zeta' - (t-s)\tilde{\lambda}_i), & u''(s) &\doteq u(s, \zeta'' - (t-s)\tilde{\lambda}_i), \\
 H(u, u_1, u_2) &\doteq l_i(u) \cdot \left((f(u_1) - \lambda_i(u)u_1) - (f(u_2) - \lambda_i(u)u_2) \right).
 \end{aligned}$$

Observing that

- $H(u, u_2, u_2) = 0$,
- $D_{u_1}H(u, u_1, u_2) = l_i(u) \cdot (Df(u_1) - \lambda_i(u)I)$,
- $D_{u_1}H(u, u, u_2) = l_i(u) \cdot (Df(u) - \lambda_i(u)I) = 0$,

we estimate

$$\begin{aligned}
 H(u, u_1, u_2) &= H(u, u_1, u_2) - H(u, u_2, u_2) \\
 &= \int_0^1 D_{u_1}H(u, u_2 + \sigma(u_1 - u_2), u_2) d\sigma \cdot (u_1 - u_2) \\
 &= \int_0^1 [D_{u_1}H(u, u_2 + \sigma(u_1 - u_2), u_2) - D_{u_1}H(u, u, u_2)] d\sigma \cdot (u_1 - u_2) \\
 &= \mathcal{O}(1) \cdot (|u_1 - u| + |u_2 - u|) \cdot |u_1 - u_2|.
 \end{aligned}$$

Here $\mathcal{O}(1)$ is any function bounded by a constant that depends only on the system, i.e. on the flux f . Therefore,

$$E_i(\zeta', \zeta'') = \mathcal{O}(1) \cdot \int_{\tau}^t |u'(s) - u''(s)| \cdot (|u'(s) - \tilde{u}_k| + |u''(s) - \tilde{u}_k|) ds.$$

Recalling (3.11) and (3.13), for any $x \in J_k(s)$ we now compute

$$|u'(s) - \tilde{u}_k| \leq V(s) + |u(s, x) - u(\tau, x)| + |u(\tau, x) - \tilde{u}_k| \leq V(s) + |u(s, x) - u(\tau, x)| + V(\tau).$$

Integrating w.r.t. x over the interval $J_k(s)$, dividing by its length and using (2.2) we obtain

$$\begin{aligned}
 |u'(s) - \tilde{u}_k| &\leq V(s) + V(\tau) + \frac{1}{\text{meas}(J_k(s))} \int_{J_k(s)} |u(s, x) - u(\tau, x)| dx \\
 &= V(s) + \varepsilon + \frac{C_M(s - \tau)}{\text{meas}(J_k(s))} \doteq g(s).
 \end{aligned}
 \tag{3.17}$$

An entirely similar estimate clearly holds for $|u''(s) - \tilde{u}_k|$. Hence

$$\begin{aligned}
 E_i(\zeta', \zeta'') &= \mathcal{O}(1) \cdot \int_{\tau}^t |u'(s) - u''(s)| \cdot g(s) ds \\
 &= \mathcal{O}(1) \cdot \int_{\tau}^t \text{Tot.Var.} \left\{ u(s); \right] \zeta' - (t - s)\tilde{\lambda}_i, \zeta'' - (t - s)\tilde{\lambda}_i \left[\right\} \cdot g(s) ds \\
 &= \mathcal{O}(1) \cdot \mu_i(\right] \zeta', \zeta'' \left[).
 \end{aligned}$$

Here μ_i is the Borel measure defined by

$$\mu_i(a, b] = \int_{\tau}^t \text{Tot.Var.} \left\{ u(s); \right] a - (t - s)\tilde{\lambda}_i, b - (t - s)\tilde{\lambda}_i \left[\right\} \cdot g(s) ds,$$

for any open interval $]a, b[\subset J_k(t)$.

According to [8, Lemma 9.3], we now have

$$\begin{aligned}
 \int_{J_k(t)} |u(t, x) - U^b(t, x)| dx &= \mathcal{O}(1) \cdot \sum_{i=1}^n \int_{J_k(t)} \left| \tilde{l}_i \cdot (u(t, x) - U^b(t, x)) \right| dx \\
 &= \mathcal{O}(1) \cdot \sum_{i=1}^n \mu_i(J_k(t)) = \mathcal{O}(1) \cdot \int_{\tau}^t V(s) \cdot g(s) ds.
 \end{aligned}$$

We now observe that, for all $\tau \leq s \leq t < \tau + \frac{1}{2}(y'_k - y''_k)$, the function g introduced at (3.17) satisfies

$$g(s) \leq V(s) + \varepsilon + \frac{C_M}{y'_k - y''_{k-1} - 2(t - \tau)} \cdot (t - \tau).
 \tag{3.18}$$

This implies

$$\frac{1}{t - \tau} \int_{J_k(t)} |u(t, x) - U^b(t, x)| dx = \frac{\mathcal{O}(1)}{t - \tau} \cdot \int_{\tau}^t V(s) \cdot (V(s) + \varepsilon) ds$$

$$+ \frac{\mathcal{O}(1) \cdot C_M}{y'_k - y''_{k-1} - 2(t - \tau)} \cdot \int_{\tau}^t V(s) \, ds. \quad (3.19)$$

Since $t = \tau$ is a Lebesgue point for V , taking the limit of (3.19) as $t \rightarrow \tau+$ we thus obtain

$$\limsup_{t \rightarrow \tau+} \frac{1}{t - \tau} \int_{J_k(t)} |u(t, x) - U^b(t, x)| \, dx = \mathcal{O}(1) \cdot V(\tau) (V(\tau) + \varepsilon) = \mathcal{O}(1) \cdot \varepsilon^2. \quad (3.20)$$

6. Finally, regarding integrals of type (III), using Lemma 2.2 we obtain the bounds

$$\limsup_{h \rightarrow 0} \frac{1}{h} \int_{y'_k+h}^{y_k-h} |u(\tau + h, x) - u(\tau, x)| \, dx = \mathcal{O}(1) \cdot \varepsilon^2, \quad (3.21)$$

$$\limsup_{h \rightarrow 0} \frac{1}{h} \int_{y_k+h}^{y''_k-h} |u(\tau + h, x) - u(\tau, x)| \, dx = \mathcal{O}(1) \cdot \varepsilon^2, \quad (3.22)$$

$$\limsup_{h \rightarrow 0} \frac{1}{h} \int_{-\infty}^{y_0-h} |u(\tau + h, x) - u(\tau, x)| \, dx = \mathcal{O}(1) \cdot \varepsilon, \quad (3.23)$$

$$\limsup_{h \rightarrow 0} \frac{1}{h} \int_{y_N+h}^{+\infty} |u(\tau + h, x) - u(\tau, x)| \, dx = \mathcal{O}(1) \cdot \varepsilon. \quad (3.24)$$

7. On the other hand, it is well known [7,8] that semigroup trajectories satisfy entirely similar estimates. Indeed, at every point y the difference between the semigroup solution and the solution to a Riemann problem satisfies

$$\lim_{h \rightarrow 0+} \frac{1}{h} \int_{y-h}^{y+h} |(S_h u(\tau))(x) - U^{\sharp}_{(u; \tau, y)}(\tau + h, x)| \, dx = 0. \quad (3.25)$$

Since the total variation of $u(\tau, \cdot)$ on the open interval $]y''_{k-1}, y'_k[$ is $\leq \varepsilon$, we have

$$\limsup_{h \rightarrow 0} \frac{1}{h} \int_{y''_{k-1}+h}^{y'_k-h} |(S_h u(\tau))(x) - U^b_{(u, \tau, k)}(\tau + h, x)| \, dx = \mathcal{O}(1) \cdot \varepsilon^2. \quad (3.26)$$

Moreover, since the total variation of $u(\tau, \cdot)$ on the open intervals $]y'_k, y_k[$ and $]y_k, y''_k[$ is $\leq \varepsilon^2$, we have

$$\limsup_{h \rightarrow 0} \frac{1}{h} \int_{y'_k+h}^{y_k-h} |(S_h u(\tau))(x) - u(\tau, x)| dx = \mathcal{O}(1) \cdot \varepsilon^2, \tag{3.27}$$

$$\limsup_{h \rightarrow 0} \frac{1}{h} \int_{y_k+h}^{y''_k-h} |(S_h u(\tau))(x) - u(\tau, x)| dx = \mathcal{O}(1) \cdot \varepsilon^2, \tag{3.28}$$

and similarly

$$\limsup_{h \rightarrow 0} \frac{1}{h} \int_{-\infty}^{y_0-h} |(S_h u(\tau))(x) - u(\tau, x)| dx = \mathcal{O}(1) \cdot \varepsilon, \tag{3.29}$$

$$\limsup_{h \rightarrow 0} \frac{1}{h} \int_{y_N+h}^{\infty} |(S_h u(\tau))(x) - u(\tau, x)| dx = \mathcal{O}(1) \cdot \varepsilon. \tag{3.30}$$

8. Combining all the previous estimates, and recalling that the total number of intervals is $N \leq M\varepsilon^{-1}$, we establish the limit (3.6), proving the theorem. \square

4. Concluding remarks

The present analysis opens the door to the study of convergence and a posteriori error estimates for a wide variety of approximation schemes.

Following [9], we say that $u = u(t, x)$ is an ε -approximate solution to (1.1) if, given the time step $\varepsilon = \Delta t$, the following holds.

(AL) Approximate Lipschitz continuity. For every $\tau, \tau' \geq 0$ one has

$$\|u(\tau, \cdot) - u(\tau', \cdot)\|_{L^1} \leq M (|\tau - \tau'| + \varepsilon) \cdot \sup_{t \in [\tau, \tau']} \text{Tot.Var.}\{u(t, \cdot)\}.$$

(P $_\varepsilon$) Approximate conservation law, and approximate entropy inequality.

For every strip $[\tau, \tau'] \times \mathbb{R}$ with $\tau, \tau' \in \varepsilon\mathbb{N}$, and every test function $\varphi \in C_c^1(\mathbb{R}^2)$, there holds

$$\left| \int u(\tau, x)\varphi(\tau, x) dx - \int u(\tau', x)\varphi(\tau', x) dx + \int_{\tau}^{\tau'} \int \{u\varphi_t + f(u)\varphi_x\} dx dt \right| \tag{4.1}$$

$$\leq C\varepsilon \|\varphi\|_{W^{1,\infty}} \cdot (\tau' - \tau) \cdot \sup_{t \in [\tau, \tau']} \text{Tot.Var.}\{u(t, \cdot)\}.$$

Moreover, given a uniformly convex entropy η with flux q , assuming $\varphi \geq 0$ one has the entropy inequality

$$\begin{aligned}
 & \int \eta(u(\tau, x))\varphi(\tau, x) dx - \int \eta(u(\tau', x))\varphi(\tau', x) dx + \int \int_{\tau}^{\tau'} \{ \eta(u)\varphi_t + q(u)\varphi_x \} dx dt \\
 & \geq - C\varepsilon \|\varphi\|_{W^{1,\infty}} \cdot (\tau' - \tau) \cdot \sup_{t \in [\tau, \tau']} \text{Tot.Var.} \{ u(t, \cdot) \}.
 \end{aligned}
 \tag{4.2}$$

In the above setting, the recent paper [9] has established **a posteriori** error estimates, assuming that the total variation of $u(t, \cdot)$ remains small, so that $u(t, \cdot)$ remains inside the domain of the semigroup. However, the estimates in [9] also required a “post processing algorithm”, tracing the location of the large shocks in the approximate solution. We would like to achieve error estimates based solely on an a posteriori bound of the total variation. The possibility of such estimates is the content of the following corollary.

Corollary 4.1. *Let (1.1) be an $n \times n$ strictly hyperbolic system where each characteristic field is either genuinely nonlinear or linearly degenerate, and which admits a strictly convex entropy $\eta(\cdot)$ as in (1.8). Let S be the unique Lipschitz semigroup defined on a domain \mathcal{D} of functions with small total variation. Then, given $T, R > 0$, there exists a function $\varrho \mapsto \varrho(\varepsilon)$ with the following properties.*

- (i) ϱ is continuous, nondecreasing, with $\varrho(0) = 0$.
- (ii) Let $t \mapsto u(t) \in \mathcal{D}$ be an ε -approximate solution to (1.1), satisfying **(AL)**-**(P $_\varepsilon$)** and supported inside the interval $[-R, R]$. Then, calling $\bar{u} = u(0)$, one has

$$\|u(t) - S_t \bar{u}\|_{L^1} \leq \varrho(\varepsilon) \quad \text{for all } t \in [0, T].
 \tag{4.3}$$

Proof. If the conclusion fails, there exists a sequence of ε_n -approximate solutions $(u_n)_{n \geq 1}$, all supported inside $[-R, R]$, with $\varepsilon_n \rightarrow 0$ but

$$\sup_{t \in [0, T]} \|u_n(t) - S_t u_n(0)\|_{L^1} \geq \delta_0 > 0 \quad \text{for all } n \geq 1.
 \tag{4.4}$$

By compactness, taking a subsequence we achieve the L^1 -convergence $u_n(t) \rightarrow u(t)$, uniformly for $t \in [0, T]$. Setting $\bar{u}(x) \doteq u(0, x)$, the limit function u is thus an entropy weak solution of (1.1)-(1.2), distinct from the semigroup trajectory $S_t \bar{u}$. This contradicts the uniqueness stated in Theorem 1.1. \square

We regard the function $\varrho(\cdot)$ as a **universal convergence rate** for approximate BV solutions to the hyperbolic system (1.1). Having proved the existence of such a function, the major open problem is now to provide an asymptotic estimate on $\varrho(\varepsilon)$, as $\varepsilon \rightarrow 0$. In some sense, starting from a uniqueness theorem and deriving a uniform convergence rate is a task analogous to the derivation of quantitative compactness estimates [2–4,21]. Based on the convergence estimates already available for the Glimm scheme [5,17] and for vanishing viscosity approximations [13,18], one might guess that $\varrho(\varepsilon) \approx \sqrt{\varepsilon} |\ln \varepsilon|$. We leave this as an open question for future investigation.

Data availability

No data was used for the research described in the article.

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