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Fondo Crosta-Giovanni Franco

Subfondo

Raccolta

Fascicolo 1992-1218-TUS-CDC31

Sottofascicolo

Documento

(Allegato) 1992-1218-CDC31_Vorstellung
02

13 APR. 2023

*The 31st IEEE Conference
on Decision and Control*

Session FP-4

**Stability Estimates for
Composite Identification-and-Control Maps
Related to a Distributed Parameter System**

Giovanni Crosta

Universita' degli Studi di Milano
Dip. di Scienze dell' Informazione

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ACKNOWLEDGEMENTS

for supporting the early stages of this work:

the Italian Ministry of University (MURST 60% grants)

Overheads prepared with

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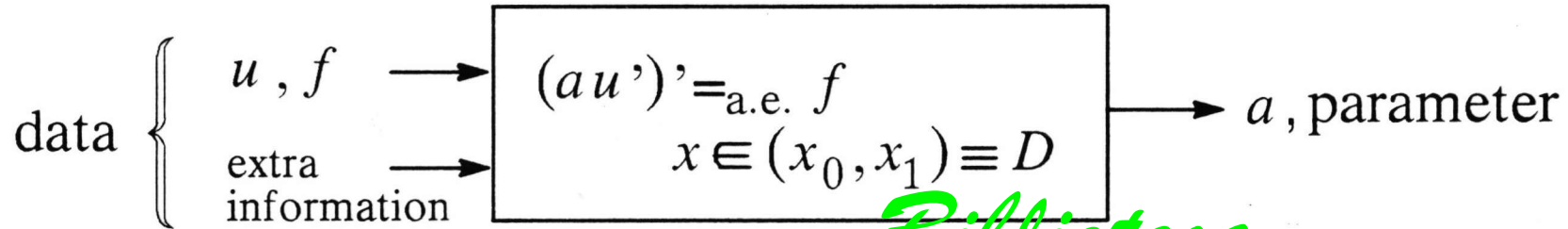
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PARADIGM

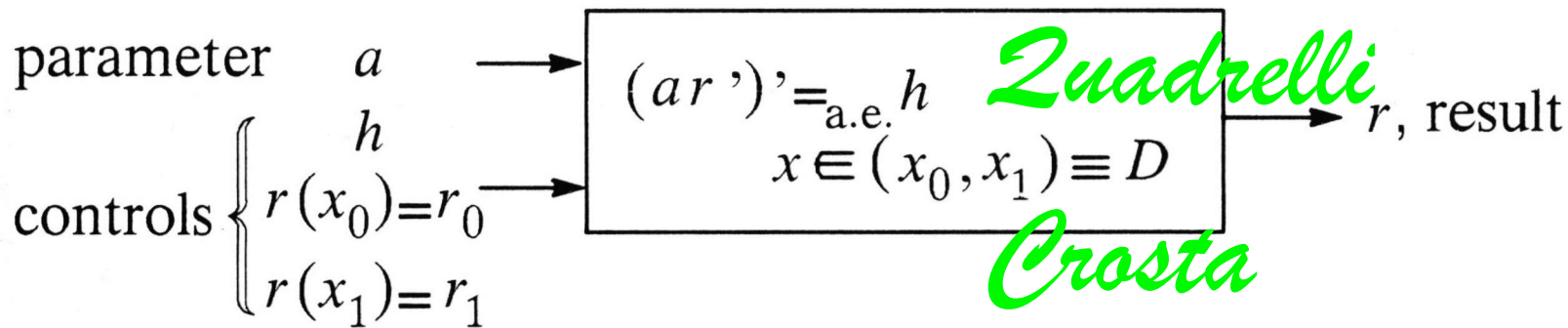
Identification for Control

INVERSE (*identification*) PROBLEM *ill - posed*



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DIRECT (*control*) PROBLEM *well - posed*



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“The solution of the ill-posed problem is only an intermediate construct intervening between the available data and the intended application”

(T. I. Seidman, 1990).

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PLAN

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Consider the composite *data – to – result* map *Quadrelli*

1 Provide some *uniqueness* conditions for the *data – to – parameter* map

1.1 from *independent* data pairs =

= *regular* Cauchy pbm. w.r. to a in $(au')' =_{a.e.} f$

1.2 from a potential *stationary* at a point =

= *singular* Cauchy pbm. w.r. to a in $(au')' =_{a.e.} f$

2 Provide the corresponding *stability* estimates for the composite map.

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1.1 – UNIQUENESS FROM INDEPENDENT DATA PAIRS

(a Regular Cauchy Problem)

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$$D := (x_0, x_1)$$

$$u, v \in C^1(\bar{D}); E_u := \{x \mid x \in \bar{D}, u'(x) = 0\}; E_v := \text{analogous}$$

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$$f, g \in L^1(D); f, g \neq 0; F(x) := \int_{x_0}^x f ds; G(x) := \int_{x_0}^x g ds$$

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$$A_{ad} := \{a \mid a \in C^0(\bar{D}), 0 < a_L \leq a(x), \forall x \in \bar{D}\}$$

Hp. $\exists a \in A_{ad} \cdot \exists \cdot \{ (au')' =_{a.e.} f, (av')' =_{a.e.} g \}$

$$E_u = E_v = \emptyset; \exists y_1, y_2 \in \bar{D} \cdot \exists \cdot \frac{1}{v'(y_1)u'(y_2)} - \frac{1}{v'(y_2)u'(y_1)} \neq 0$$

Th. $\exists! \hat{a} = \frac{F + c_1}{u'}$ (reference solution)

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$$c_1 = \frac{(G_2 - G_1)u_1' u_2' - F_2 u_1' v_2' + F_1 u_2' v_1'}{u_1' v_2' - u_2' v_1'}$$

1.2 – UNIQUENESS FROM
A POTENTIAL STATIONARY AT A (CRITICAL) POINT
(a Singular Cauchy Problem)

Hp. $\exists a \in A_{ad} \cdot \exists \cdot \{ (au')' =_{a.e.} f \}$

$$E_u = \{ x_u \}$$

Th. $\exists! \hat{a} = \frac{F - F(x_u)}{u'}$ (reference solution)

Rem.: special case of Kitamura – Nakagiri (1977) uniqueness prop.

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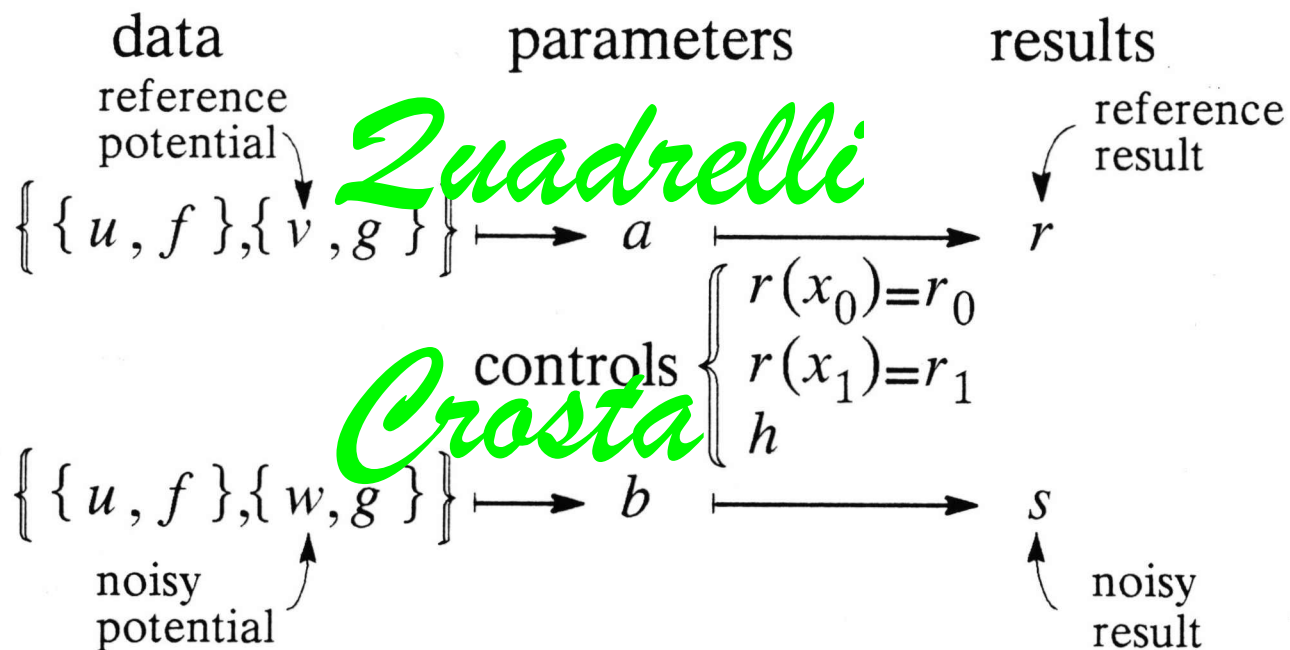
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2.1 – STABILITY OF THE DATA – TO – RESULT MAP

Regular Cauchy Problem, begin

Target:

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$$\| s - r \|_Z \leq c_I(D, f, g, h, u, r_0, r_1, a_L, a_H) \| w - v \|_V$$

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2.1 – STABILITY OF THE DATA – TO – RESULT MAP

Regular Cauchy Problem, end

Hp. (additional, w.r. to uniqueness statement)

$$\|f\|_1, \|g\|_1 \leq c_s;$$

$$|u_i^?|, |v_i^?| \leq c_P, \quad i = 1, 2 \quad (\text{noiseless potentials only})$$

$$|u_i^?| \geq c_M \quad \leftarrow \text{ // uniqueness from singular Cauchy problem}$$

$$|v_2^? u_1^? - v_1^? u_2^?|, |w_2^? u_1^? - w_1^? u_2^?| \geq \frac{1}{c_T}$$

$$a \leq a_H \quad \leftarrow \text{ No such constraint for } b!$$

$$\left| \frac{r_1 - r_0}{x_1 - x_0} \right| \leq c_r; \quad \|h\|_1 \leq c_h$$

Th. i) $Z = W^{1,\infty}(D); V = \{w_i^? - v_i^? \mid i = 1, 2\}$

ii) (uniform estimate)

$$\|s^? - r^?\|_{\infty} \leq C_0 (C_1 \Delta_{21} + C_2 \Delta_{21}^2)$$

$$\Delta_i := |w_i^? - v_i^?|, \quad i = 1, 2; \quad \Delta_{21} = 2 c_P^3 c_s c_T^2 (\Delta_2 + \Delta_1)$$

$$C_0 = \frac{a_H}{a_L^2 c_M} (c_r + \frac{c_h}{a_L}); \quad C_1 = 1 + \frac{a_H}{a_L}; \quad C_2 = \frac{1}{a_L c_M}$$

iii) ($W^{1,\infty}$ – norm estimate)

$$\|r - s\|_{1, \infty} \leq (1 + |x_1 - x_0|) \|s^? - r^?\|_{\infty}$$

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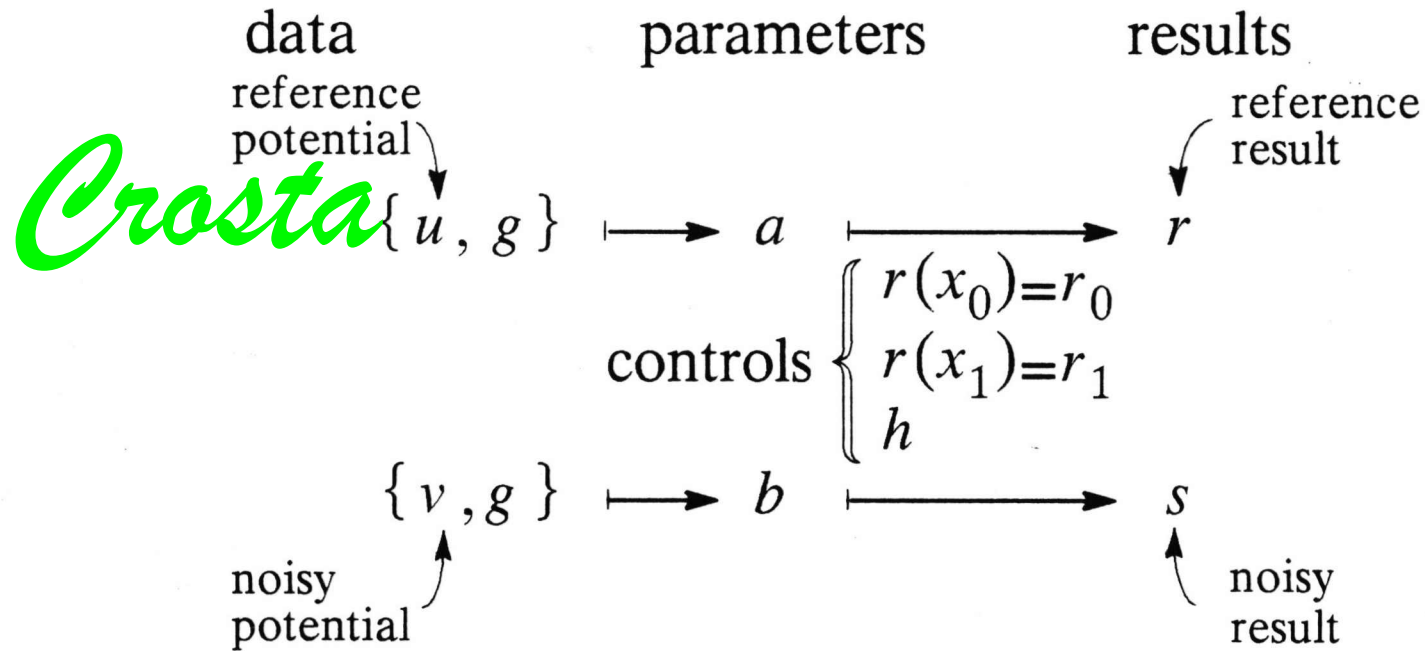
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2.2 – STABILITY OF THE DATA – TO – RESULT MAP:

Singular Cauchy Problem, begin

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2.2 – STABILITY OF THE DATA – TO – RESULT MAP

Singular Cauchy Problem, end

Hp. (additional, w.r. to uniqueness statement)

$$\left\| \frac{1}{u'} \right\|_1, \left\| \frac{1}{v'} \right\|_1 \leq c_v \quad \longleftarrow \text{major difference w.r. to}$$

uniqueness from independence)

Th. i) $Z = W^{1,1}(D)$; $V = W^{1,\infty}(D)$

ii) (estimate, $E_u = E_v = \{x_u\}$)

$$\|s' - r'\|_1 \leq 4 \frac{a_H^2}{a_L^2} c_v \left(c_r + \frac{c_h}{a_L} \right) \|v' - u'\|_\infty$$

c_r, c_h, a_H, a_L : usual meaning.

Rem.

Given the two point BV control pbm, $\|s' - r'\|_1$ is equivalent to
the natural norm of $W^{1,1}$.

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2.3 – STABILITY OF THE DATA – TO – RESULT MAP

Conclusion

Independent data \Rightarrow *Biblioteca*
 \Rightarrow regular Cauchy problem for $a \cdot \exists \cdot (au')' =_{a.e.} f \Rightarrow$
 $\Rightarrow L^{\infty}$ – estimate for the data – to – parameter map.

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Stationary potential e.g., $E_u = \{ x_u \} \Rightarrow$
 \Rightarrow singular Cauchy problem \Rightarrow
 $\Rightarrow L^1$ – estimate. *Crosta*

The *parameter – to – result* problem is well – posed.

The stability of the composite map inherits the stability of the *data*
– to – *parameter* map.

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