

ASIDE:

## A GROWTH ESTIMATE

Lemma 1

IF  $B \in \mathbb{B}_{ad}$ ;  $\frac{\phi_{xx}}{\phi_x} \in L^1(D)$ ;

AND  $(\frac{\rho}{\phi_x})^{[-1]} \in L^\infty(D)$ ;  $\exists \lim_{x \rightarrow x_0^+} (\frac{\rho}{\phi_x})^{[-1]}$

AND  $B_x \phi_x + B \phi_{xx} - \rho =_{d.w.} 0$

THEN

$$\|B\|_{0,\infty} \leq \|(\frac{\rho}{\phi_x})^{[-1]}\|_{0,\infty} \exp[\|\frac{\phi_{xx}}{\phi_x}\|_{0,1}]$$

Proof:

relies on extended form of Gronwall – Bellman inequality

$D = (x_0, x_1)$ ;  $a \in \mathbb{A}_{ad}$ ;

$g \in \mathbb{G}_{ad} := \{g \mid g \in L^1(D), g \geq_{a.e.} 0\}$

$c_+ \geq 0$  (constant)

IF  $a \leq c_+ + \int_{x_0}^x ag \, d\xi$ , a.e. in  $D$

THEN

$$\|a\|_{0,\infty} \leq c_+ \exp \|g\|_{0,1}$$

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# STABILITY ESTIMATES: 2 – APPLICATION TO LAYERED MEDIA

Rem.: (Implications of  $H_p$ .)

$$a' = \sum_{i=1}^{\infty} c_i \delta(x - \xi_i) + \sum_{i=1}^{\infty} \psi_i \chi_{(\xi_i, \xi_{i+1})},$$

$$\sum_{i=1}^{\infty} |c_i| < \infty, \text{ etc. } \Rightarrow$$

i)  $|\hat{a}_x|_0^{[-1]} \subset L^\infty(D);$

rules out e.g.,  $a = 2 + \sin \frac{1}{x}$  in  $[-1, +1]$

ii)  $\exists \lim_{x \rightarrow x_0^+} \hat{a}; \exists \lim_{x \rightarrow x_1^-} \hat{a}$

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# STABILITY ESTIMATES:

## 3 – SINGULAR CAUCHY – UNIQUE SOLN.

Let  $\bar{I} \subset D$

Thm.

IF  $u, v \in \mathbf{X}$

$$\exists \tau \in \bar{I} \cdot \exists \cdot \left(\frac{1}{u_x}\right)(\tau) \in L^1(D) ;$$

$$(*) \quad E_u(\tau) \neq \emptyset \wedge \{\text{meas}[E_u(\tau)] = 0\}$$

$$E_v(\tau) \neq \emptyset, \text{meas}[E_v(\tau)] \geq 0$$

$$E_u(\tau) \subset \bar{I}, \quad E_v(\tau) \subset \bar{I}$$

$$\left(\frac{1}{v_x}\right)(\tau) \in L^1(D \setminus E_v(\tau)) := \mathbf{Y}(\tau)$$

$$\left\| \frac{1}{v_x} \right\|_{\mathbf{Y}_\tau} \leq c_v$$

$$\exists \hat{a}(u, f) \in \mathbf{A}_{ad} \cap C^0(\bar{I})$$

$$\exists b(v, f) \in \mathbf{A}_{ad}$$

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THEN

$$\|B\|_{0,1} \leq c_v [1 + 2\|\hat{a}\|_{0,\infty}] \|V\|_{\mathbf{X}_\tau}$$

Rem.

i) Second conductivity,  $b$ , need not be unique.

ii) Same estimate from uniqueness condition (\*\*); much more complicated proof.

# STABILITY ESTIMATES: 4 – SYNOPSIS OF PROOFS

Regular Cauchy

Singular Cauchy (\*)

$$B := b - a ; V := v - u ; r := -V_t + (aV_x)_x$$

starting point: the *defect* equation

$$(Bv_x)_x + r =_{\text{d.w.}} 0 \text{ @ } t = \tau$$

$$B(x_0) = 0$$

$$(Bv_x)(\xi^+_{\nu}(\tau), \tau) = 0$$

$$r^{[-1]} = -V_t^{[-1]} + \hat{a} V_x + \text{const.}$$

$$B_x = -\frac{r}{v_x} - B \frac{v_{xx}}{v_x}$$

$$Bv_x =_{\text{a.e.}} -(r_0^{[-1]})(\tau)$$

apply Gronwall – Bellman  
inequality and Lemma 1

need  $\exists \hat{a}(\xi_{\nu}(\tau))$  now

$$R := \frac{r}{v_x}$$

$$B =_{\text{a.e.}} -\left(\frac{r_0^{[-1]}}{v_x}\right)(\tau)$$

$$\|B\|_{0,\infty} \leq$$

$$\|B\|_{0,1} \leq$$

$$\leq [\|R_0^{[-1]}\|_{0,\infty} \exp\|\frac{v_{xx}}{v_x}\|](\tau)$$

$$\leq c_{\nu} \|r_0^{[-1]}\|_{0,\infty}(\tau)$$

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bring in  $V$  instead of  $R$ , resp.  $r$  ;  
all remaining Hp. on data used up here

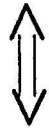
CONCLUSION:

$L^{\infty}$ -estimates

$L^1$ -estimates

# STABILITY ESTIMATES: 5 – INCOMPATIBLE CONDITIONS

$$\left(\frac{v_{xx}}{v_x}\right)(\tau) \in L^1(D) \quad \# \quad (Bv_x)(\xi^+ v(\tau), \tau) = 0$$



$$\frac{1}{v_x} \in AC(\bar{D})$$

necessary for the non-  
uniqueness of  $b(v, f)$ ,  
given existence

$$\frac{1}{v_x} \in L^1(\bar{D})$$



$L^1$ - estimate

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Related results:

Baumeister & Kunisch, 1991, *Applicable Analysis*

Marcellini, 1982, *Ric. di Matem. dell' Univ. di Napoli*

# CONCLUSION

- i)* Defect equation as main device.
- ii)* Cauchy problem thereof.
- iii)* Unified view over  
uniqueness conditions and stability estimates.
- iv)* Supplementary (regularization) conditions needed to attain stability estimates.
- v)* Admissible  $a$  in stability estimates affected by type of Cauchy problem:  
 $a$  bounded, measurable when Cauchy pbm. regular;  
continuity of  $a$  @ critical points cannot be relaxed.
- vi)* Application to time – independent inverse problems:  
technically straightforward;  
distinction between regular and singular Cauchy problems left unaltered;  
same stability estimates.

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