

COHOMOGENEITY ONE EINSTEIN-SASAKI 5-MANIFOLDS

DIEGO CONTI

ABSTRACT. We consider hypersurfaces in Einstein-Sasaki 5-manifolds which are tangent to the characteristic vector field. We introduce evolution equations that can be used to reconstruct the 5-dimensional metric from such a hypersurface, analogous to the (nearly) hypo and half-flat evolution equations in higher dimensions. We use these equations to classify Einstein-Sasaki 5-manifolds of cohomogeneity one.

INTRODUCTION

From a Riemannian point of view, an Einstein-Sasaki manifold is a Riemannian manifold (M, g) such that the conical metric on $M \times \mathbb{R}^+$ is Kähler and Ricci-flat. In particular, this implies that (M, g) is odd-dimensional, contact and Einstein with positive scalar curvature. The Einstein-Sasaki manifolds that are simplest to describe are the *regular* ones, which arise as circle bundles over Kähler-Einstein manifolds. In five dimensions, there is a classification of regular Einstein-Sasaki manifolds [12], in which precisely two homogeneous examples appear, namely the sphere S^5 and the Stiefel manifold

$$(1) \quad V_{2,4} = \mathrm{SO}(4)/\mathrm{SO}(2) \cong S^2 \times S^3 .$$

In fact these examples are unique (up to finite cover), as homogeneous contact manifolds are necessarily regular [3]. Among regular Einstein-Sasaki 5-manifolds, these two are the only ones for which the metric is known explicitly: indeed, the sphere is equipped with the standard metric, and the metric on $V_{2,4}$ has been described in [20]. Notice however that both S^5 and $S^2 \times S^3$ carry other, non-regular Einstein-Sasaki metrics [4, 5].

Only recently other explicit examples of Einstein-Sasaki manifolds have been found, as in [13] the authors constructed an infinite family $Y^{p,q}$ of Einstein-Sasaki metrics on $S^2 \times S^3$ (see also [10] for a generalization). These metrics are non-regular, and thus they are not included in the above-mentioned classification. The isometry group of each $Y^{p,q}$ acts with cohomogeneity one, meaning that generic orbits are hypersurfaces. In this paper we give an alternative construction of the $Y^{p,q}$, based on the language of cohomogeneity one manifolds. In fact we prove that, up to finite cover, they are the only Einstein-Sasaki 5-manifolds on which the group of isometries acts with cohomogeneity one. In particular, this result settles a question raised in [14], concerning the family of links $L(2, 2, 2, k)$, $k > 0$ defined by the polynomial

$$z_1^2 + z_2^2 + z_3^2 + z_4^k .$$

The homogeneous metrics mentioned earlier provide examples of Einstein-Sasaki metrics on $L(2, 2, 2, k)$, $k = 1, 2$ such that the integral lines of the characteristic

vector field are the orbits of the natural action of $U(1)$ with weights $(k, k, k, 2)$. The authors of [14] show that for $k > 3$ no such metric exists. Since $L(2, 2, 2, 3)$ is diffeomorphic to S^5 , and a metric on $L(2, 2, 2, 3)$ of the required type would necessarily be of cohomogeneity one, our classification extends this result to $k \geq 3$.

In five dimensions, another characterization of Einstein-Sasaki manifolds is by the existence of a real Killing spinor or, more precisely, a spinor satisfying

$$\nabla_X \psi = -\frac{1}{2} X \cdot \psi ,$$

where ∇ is the Levi-Civita connection and \cdot denotes Clifford multiplication. Such a spinor exists on every Einstein-Sasaki manifold in any dimension. The converse only fails to be true to the extent that a complete simply-connected Riemannian manifold which admits a real Killing spinor but no Einstein-Sasaki structure is either a sphere S^{2n} , a 7-manifold with a nearly-parallel G_2 structure or a nearly-Kähler 6-manifold [1]. In all of these cases the metric is Einstein with positive scalar curvature. Thus, Einstein-Sasaki manifolds can be viewed as part of a slightly more general class. We shall not make much use of the spinor formalism in this paper, because once one fixes the dimension, the spinor can be replaced with differential forms. However, the characterization in terms of spinors establishes an analogy which is suggestive of the fact that the methods of this paper can be adapted to the nearly-Kähler case, potentially leading to the construction of non-homogeneous nearly-Kähler 6-manifolds. This expectation is supported by the fact that the corresponding exterior differential system is involutive in the nearly-Kähler as in the Einstein-Sasaki case. As far as the author knows, the only known examples of nearly-Kähler 6-manifolds are homogeneous (see [7] for a classification). On the other hand, cohomogeneity one nearly-parallel G_2 manifolds are classified, and none of them is complete [8].

Our method to classify cohomogeneity one Einstein-Sasaki 5-manifolds consists in considering a generic orbit, which by hypothesis is a hypersurface. We prove that it is tangent to the characteristic vector field; this fact enables us to define an induced global frame on the hypersurface, and write down certain equations that it must satisfy. Resuming the analogy with higher dimensions, these equations correspond to the nearly hypo and nearly half-flat equations of [11]. In general, a hypersurface in an Einstein-Sasaki 5-manifold (which we take to be tangent to the characteristic vector field) determines the Einstein-Sasaki structure locally. We express this fact in terms of evolution equations like in [16, 9, 11]. These evolution equations are of independent interest, as their solutions correspond to local Einstein-Sasaki metrics; the fact that a solution always exists for real analytic initial conditions is not obvious, but it follows from the exterior differential system being involutive. However, this is not essential to our classification: all we need to do is find all homogeneous solutions of our nearly-hypo-like equations, and solve the evolution equations explicitly in an interval (t_-, t_+) , with these solutions as initial conditions. Having done that, we prove that for suitable choices of the parameters the resulting metric can somehow be extended to the boundary of (t_-, t_+) , leading to cohomogeneity one manifolds with an invariant Einstein-Sasaki metric. Conversely, all such Einstein-Sasaki 5-manifolds are obtained this way. This construction is similar to the one of [8], where cohomogeneity one manifolds with (weak) holonomy G_2 were classified. However, such manifolds are non-compact, in

sharp contrast with our case. Indeed, the metrics we obtain appear to be the first compact examples obtained by an evolution in the sense of [16].

1. INVARIANT EINSTEIN-SASAKI $SU(2)$ -STRUCTURES

In the usual terminology, an Einstein-Sasaki structure on a 5-manifold is a type of $U(2)$ -structure. However, simply connected Einstein-Sasaki manifolds carry a real Killing spinor [12], which reduces the structure group to $SU(2)$. The relevant representation of $SU(2)$ can be described by the diagram

$$\begin{array}{ccccc} SU(2)_- & \hookrightarrow & SU(2)_+ \times SU(2)_- & \xrightarrow{\cong} & Spin(5) \\ \parallel & & \downarrow 2:1 & & \downarrow 2:1 \\ SU(2) & \longrightarrow & SO(4) & \longrightarrow & SO(5) \end{array}$$

Giving an $SU(2)$ -structure on a 5-manifold \mathbf{M} is the same as giving differential forms $(\alpha, \omega_1, \omega_2, \omega_3)$, such that locally there exists a basis of orthonormal forms e^1, \dots, e^5 satisfying

$$(2) \quad \begin{cases} \alpha = e^5 & \omega_1 = e^{12} + e^{34} \\ \omega_2 = e^{13} + e^{42} & \omega_3 = e^{14} + e^{23} \end{cases}$$

Here and in the sequel, we abbreviate $e^1 \wedge e^2$ as e^{12} , and so on. By [9], the Einstein-Sasaki condition can be written

$$(3) \quad d\alpha = -2\omega_1, \quad d\omega_2 = 3\alpha \wedge \omega_3, \quad d\omega_3 = -3\alpha \wedge \omega_2.$$

By this we mean that, up to passing to the universal cover, every Einstein-Sasaki $U(2)$ -structure on a 5-manifold has an $SU(2)$ -reduction satisfying (3).

Remark. The constant 3 appearing in Equation (3) is in some sense not essential: one could replace it with an unspecified constant, obtaining a possible definition of an α -Einstein-Sasaki $SU(2)$ -structure. Most of our arguments generalize to this more general setting in a straightforward way. However, since this paper is mainly concerned with cohomogeneity one metrics, we shall focus on the Einstein case, as the generalization does not seem to produce any new example.

We are interested in Einstein-Sasaki manifolds \mathbf{M} of cohomogeneity one, namely those for which the principal orbits of the isometry group are hypersurfaces. Since we require \mathbf{M} to be complete, and Einstein-Sasaki manifolds have positive Ricci, by Myers' theorem \mathbf{M} will be compact with finite fundamental group. We shall assume that \mathbf{M} is simply connected, which amounts to passing to the universal cover. In this hypothesis, we now prove some facts that play an important rôle in the classification. Recall that the *characteristic vector field* is by definition the vector field dual to α .

Lemma 1. *Let a compact Lie group G act on a contact manifold \mathbf{M} with cohomogeneity one, preserving the contact form. Then the characteristic vector field is tangent to each principal orbit.*

Proof. Let α be the contact form, and let \mathbf{M} have dimension $2n + 1$. On every principal orbit Gx we have

$$(d\alpha)^n = d(\alpha \wedge (d\alpha)^{n-1});$$

by Stokes' Theorem,

$$0 = \int_{Gx} (d\alpha)^n .$$

On the other hand, $(d\alpha)^n$ is invariant under G , so it must vanish identically. Now observe that at each point x , the characteristic direction is the space

$$\{X \in T_x \mathbf{M} \mid X \lrcorner (d\alpha)^n = 0\} ;$$

the statement follows immediately. \square

Lemma 2. *Let \mathbf{M} be a compact, simply-connected, Einstein-Sasaki 5-manifold. Suppose that the group of isometries of \mathbf{M} acts with cohomogeneity one. Then the action of its identity component \mathcal{I} preserves the Einstein-Sasaki $U(2)$ -structure of \mathbf{M} , and one can define a homomorphism*

$$e^{i\gamma} : \mathcal{I} \rightarrow U(1), \quad L_g^*(\omega_2 + i\omega_3) = e^{i\gamma}(g)(\omega_2 + i\omega_3) .$$

If \mathcal{I} has dimension greater than four, $\mathcal{I}' = \ker e^{i\gamma}$ is a 4-dimensional Lie group that acts on \mathbf{M} with cohomogeneity one, beside preserving the Einstein-Sasaki $SU(2)$ -structure.

Proof. The action of \mathcal{I} preserves both metric and orientation on \mathbf{M} , and therefore the spin structure. Thus, \mathcal{I} acts on the space of spinors $\Gamma(\Sigma)$, and the space $\mathcal{K} \subset \Gamma(\Sigma)$ of Killing spinors with Killing constant $-1/2$ is preserved by \mathcal{I} . By the assumption on the isometry group, \mathbf{M} is not isometric to the sphere. Hence, \mathcal{K} is a complex vector space of dimension one (see [12]), and it determines the $U(2)$ -structure of \mathbf{M} . The action of \mathcal{I} on $\mathcal{K} \cong \mathbb{C}$ determines the homomorphism $e^{i\gamma}$.

Suppose \mathcal{I} has dimension greater than four, and let K be the stabilizer at a point of a principal orbit M ; by dimension count, K is not discrete. We claim that

$$(4) \quad \mathfrak{k} \oplus \mathfrak{i}' = \mathfrak{i} ,$$

where \mathfrak{k} , \mathfrak{i} , \mathfrak{i}' are the Lie algebras of K , \mathcal{I} and \mathcal{I}' respectively. We shall prove by contradiction that \mathfrak{k} is not contained in \mathfrak{i}' , which implies (4) by a dimension count.

The principal orbit M has trivial normal bundle, and the unit normal is invariant. Since the action of \mathcal{I} preserves \mathcal{K} , it also preserves the contact form, and so by Lemma 1 the characteristic vector field is tangent to M . Consequently, the unit normal is an invariant section of $\ker \alpha|_M$. The structure group $SU(2)$ acts freely on unit vectors in $\mathbb{R}^4 = \ker e^5$, and so \mathcal{I}' preserves an $\{\text{Id}\}$ -structure on M . Hence $\mathfrak{k} \subset \mathfrak{i}'$ acts trivially on $\mathfrak{i}/\mathfrak{k}$, implying that \mathfrak{k} is an ideal of \mathfrak{i} . Then the identity component of K is a normal subgroup of \mathcal{I} , and so it acts trivially on \mathbf{M} ; since \mathcal{I} acts effectively, this implies that K is discrete, which is absurd. Thus, (4) holds and \mathcal{I}' acts with cohomogeneity one.

By the same token, the stabilizer $\mathcal{I}' \cap K$ has trivial isotropy representation and is therefore normal in \mathcal{I}' . But then it is also normal in \mathcal{I} , which acts effectively, implying that $\mathcal{I}' \cap K$ is the trivial group and \mathcal{I}' acts freely on M . In particular, \mathcal{I}' has dimension equal to four. \square

Remark. Part of the argument of Lemma 2 was exploited in [18] to prove that unit Killing fields do not exist on nearly-Kähler 6-manifolds other than $S^3 \times S^3$. The 6-dimensional case is simpler in this respect, because Killing spinors form a *real* vector space of dimension one. Thus, a Lie group acting isometrically on a nearly-Kähler 6-manifold automatically preserves the nearly-Kähler $SU(3)$ -structure.

It will follow from our classification that the isometry group of \mathbf{M} has dimension five, but we cannot prove it directly. The best that we can do at the moment is the following:

Proposition 3. *If \mathbf{M} is a simply-connected compact Einstein-Sasaki 5-manifold of cohomogeneity one, then the Lie group $\mathrm{SU}(2) \times \mathrm{U}(1)$ acts on \mathbf{M} with cohomogeneity one preserving the Einstein-Sasaki $\mathrm{U}(2)$ -structure, and each principal stabilizer K is a finite subgroup of a maximal torus $\mathrm{T}^2 \subset \mathrm{SU}(2) \times \mathrm{U}(1)$.*

Proof. Since the isometry group acts with cohomogeneity one, its dimension is greater than or equal to four. If greater, by Lemma 2 there is a four-dimensional subgroup that acts with cohomogeneity one. Thus, there is a four-dimensional compact Lie group G that acts with cohomogeneity one. Up to finite cover, G is either a torus or $\mathrm{SU}(2) \times \mathrm{U}(1)$. Under the projection $G \rightarrow G/K \cong M$, where M is a principal orbit, the invariant one-form α pulls back to a non-closed left-invariant one-form on G . No such form exists on a torus, and so we can assume that G is $\mathrm{SU}(2) \times \mathrm{U}(1)$.

Now, the stabilizer K is discrete, because G acts with cohomogeneity one, and compact, because G is; hence, K is finite. The tangent space of a principal orbit splits as

$$TM = G \times_K (\mathfrak{su}(2) \oplus \mathfrak{u}(1)) = G \times_K \mathfrak{su}(2) \oplus G \times_K \mathfrak{u}(1)$$

into two integrable distributions. Since $\ker \alpha$ is not integrable on M ,

$$\ker \alpha|_M \neq G \times_K \mathfrak{su}(2) .$$

Thus α has a non-zero component in $G \times_K (\mathfrak{su}(2))^*$. On the other hand, the subgroup of G that fixes a non-zero element in $\mathfrak{su}(2)^*$ is a maximal torus T^2 . Since α is fixed by the isotropy representation, it follows that $K \subset \mathrm{T}^2$. \square

2. COHOMOGENEITY ONE

In this section we recall some standard facts and notation concerning cohomogeneity one manifolds, referring to [6] for the details. Like in the statement of Proposition 3, in this section \mathbf{M} is a compact simply-connected manifold on which a Lie group G acts with cohomogeneity one.

By the general theory of cohomogeneity one manifolds, the orbit space \mathbf{M}/G is a one-dimensional manifold, which by our topological assumptions is a closed interval. More precisely, we can fix an interval $I = [t_-, t_+]$ and a geodesic $c: I \rightarrow \mathbf{M}$ that intersects principal orbits orthogonally, so that the induced map

$$I \rightarrow \mathbf{M}/G$$

is a homeomorphism. The stabilizer of $c(t)$ is fixed on the interior of I , and we can define

$$H_{\pm} = \mathrm{Stab} c(t_{\pm}), \quad K = \mathrm{Stab} c(t), \quad t \in (t_-, t_+) .$$

Then $H_{\pm} \supset K$, and moreover there is a sphere-transitive orthogonal representation V_{\pm} of H_{\pm} with principal stabilizer K . By the simply-connectedness assumption, V_{\pm} has dimension greater than one, so that H_{\pm}/K is diffeomorphic to a sphere of positive dimension.

The orbits $Gc(t_{\pm}) \cong G/H_{\pm}$ are called *special*. In a neighbourhood of each special orbit, \mathbf{M} is G -equivariantly diffeomorphic to an associated bundle

$$(5) \quad G \times_{H_{\pm}} D_{\pm} \subset G \times_{H_{\pm}} V_{\pm} ,$$

where D_{\pm} is the closed unit disk in V_{\pm} . One can reconstruct \mathbf{M} by glueing together two disk bundles of the form (5) along the boundaries, namely along the sphere bundles $G \times_{H_{\pm}} \partial D_{\pm}$. By hypothesis these boundaries consist of a single principal orbit; identifying both of them with G/K , the glueing map is defined by a G -equivariant automorphism of G/K . All such automorphisms have the form

$$gK \rightarrow gaK, \quad a \in N(K).$$

It is customary to represent any cohomogeneity one manifold obtained this way by the diagram

$$(6) \quad K \subset \{H_-, H_+\} \subset G.$$

Strictly speaking, this diagram does not determine \mathbf{M} (up to G -equivariant diffeomorphism), because the glueing map is also involved. However in many cases, e.g. if $N(K)$ is connected, any glueing map can be extended to an equivariant diffeomorphism of at least one of the two disk bundles, and so all maps give the same manifold up to equivariant diffeomorphism (see [21] for details).

More specifically to our case, by Proposition 3 K is a finite subgroup of $T^2 \subset G$. Since H_{\pm}/K is diffeomorphic to a sphere, each H_{\pm} can be either one-dimensional or three-dimensional. However, since \mathbf{M} is simply-connected, H_+ and H_- cannot both be three-dimensional (see e.g. [15]). If H_{\pm} is three-dimensional, then its identity component is $(H_{\pm})_0 = \mathrm{SU}(2) \times \{1\}$ and $H_{\pm} = K \cdot (H_{\pm})_0$. Now

$$S^3 \cong \frac{H_{\pm}}{K} = \frac{(H_{\pm})_0}{(H_{\pm})_0 \cap K}$$

and thus $K \cap (\mathrm{SU}(2) \times \{1\})$ is the trivial group. It follows that the tube about the special orbit G/H_{\pm} satisfies

$$(7) \quad G \times_{H_{\pm}} V_{\pm} = G \times_{(H_{\pm})_0} V_{\pm}.$$

Concerning the case that H_{\pm} is one-dimensional, we remark that if one assumes that H_{\pm} is contained in T^2 , then K is normal in H_{\pm} . Then K acts trivially in the slice representation, and again (7) holds. These facts will be used in the proof of Lemma 9.

3. EVOLUTION AND HYPERSURFACES

We now introduce a convenient language to determine the cohomogeneity one metrics in terms of the invariant structure induced on a principal orbit. This section is motivated by Section 1, but otherwise independent, and should be read in the context of evolution equations in the sense of [16].

In this section, M is an oriented hypersurface in a 5-manifold \mathbf{M} with an $\mathrm{SU}(2)$ -structure; notice that we make no hypotheses of invariance. Let X be the unit normal to M , compatible with the orientations. One can measure the amount to which α fails to be tangent to M by the angle

$$\beta: M \rightarrow [-\pi/2, \pi/2], \quad \sin \beta = \iota^*(\alpha(X)).$$

The relevant case for our classification is $\beta \equiv 0$ (Lemma 1).

Remark. If α is a contact form on \mathbf{M} , the angle β cannot equal $\pm\pi/2$ on an open subset of M , as that would mean that the distribution $\ker \alpha$ is integrable.

Given a hypersurface $\iota: M \rightarrow \mathbf{M}$, one can look for deformations of ι that leave β unchanged. Under suitable integrability assumptions on \mathbf{M} , there is a canonical deformation obtained by the exponential map with this property. We shall say that an $SU(2)$ -structure is *contact* if the underlying almost contact metric structure is contact, i.e. $d\alpha = -2\omega_1$, and it is *K-contact* if in addition the characteristic vector field is Killing. There is a well-known characterization of *K-contact* structures [2], which in our language reads

$$\nabla_X \alpha = -2X \lrcorner \omega_1 \quad \forall X \in T\mathbf{M} ,$$

where ∇ is the Levi-Civita connection.

Lemma 4. *Let \mathbf{M} be a K-contact 5-manifold and let $\iota: M \rightarrow \mathbf{M}$ be an oriented, compact embedded hypersurface. Consider the one-parameter family of immersions $\iota_t: M \rightarrow \mathbf{M}$ given by*

$$\iota_t(x) = \exp_{\iota(x)}(tX_x) ,$$

where X is the unit normal. Then the angle $\beta_t: M \rightarrow [-\pi/2, \pi/2]$ of the hypersurface $\iota_t: M \rightarrow \mathbf{M}$ does not depend on t .

Proof. Using the exponential map, we can extend X to a neighbourhood of M , in such a way that X is normal to all of the $\iota_t(M)$ for small t . We must prove

$$(8) \quad \iota_t^*(\alpha(X)) = \iota^*(\alpha(X)) ,$$

which holds trivially for $t = 0$. By the definition of the exponential map, $\nabla_X X = 0$. So,

$$\mathcal{L}_X(\alpha(X)) = (\nabla_X \alpha)(X) = (-2X \lrcorner \omega_1)(X) = 0 ,$$

and (8) holds for all t . \square

With notation from Lemma 4, the exponential map produces an inclusion

$$M \times (t_-, t_+) \ni (x, t) \rightarrow \iota_t(x) \in \mathbf{M} ;$$

with respect to which the Riemannian metric \mathbf{g} on \mathbf{M} pulls back to a metric in the “generalized cylinder form” $dt^2 + \iota_t^* \mathbf{g}$. Using Lemma 4, we can do the same for the $SU(2)$ -structure:

Proposition 5. *Let $\iota: M \rightarrow \mathbf{M}$ be a compact, oriented hypersurface with angle $\beta = 0$ in a K-contact 5-manifold $(\mathbf{M}, \alpha, \omega_i)$. Then there is a one-parameter family of $\{\text{Id}\}$ -structures $(\eta^0(t), \dots, \eta^3(t))$ on M satisfying*

$$\eta^0(t) = \iota_t^* \alpha , \quad \eta^{23}(t) = \iota_t^* \omega_1 , \quad \eta^{31}(t) = \iota_t^* \omega_2 , \quad \eta^{12}(t) = \iota_t^* \omega_3 ,$$

and \mathbf{M} is locally given as the product $M \times (t_-, t_+)$, with $SU(2)$ -structure determined by

$$\begin{aligned} \alpha &= \eta^0(t) , & \omega_1 &= \eta^{23}(t) + \eta^1(t) \wedge dt , \\ \omega_2 &= \eta^{31}(t) + \eta^2(t) \wedge dt , & \omega_3 &= \eta^{12}(t) + \eta^3(t) \wedge dt . \end{aligned}$$

Proof. Let x be a point of $\iota_t(M)$. Choose a basis e^1, \dots, e^5 of $T_x^* \mathbf{M}$ such that Equations 2 hold. Using the metric on \mathbf{M} , we can write

$$T_x^* \mathbf{M} = T_x^* \iota_t(M) \oplus \langle dt \rangle ,$$

where dt represents the unit normal 1-form compatible with the orientations. By Lemma 4, e^5 lies in $T_x^* \iota_t(M)$. We can act on e^1, \dots, e^5 by some element of $SU(2)$ to obtain $e^4 = dt$. Then

$$\eta^0 = e^5, \quad \eta^1 = e^3, \quad \eta^2 = -e^2, \quad \eta^3 = e^1, \quad dt = e^4. \quad \square$$

It is well known that Einstein-Sasaki manifolds are K -contact. In the hypotheses of Proposition 5, assume that (α, ω_i) satisfy (3). Then it is clear that for all t , the following hold:

$$(9) \quad d\eta^0 = -2\eta^{23}, \quad d\eta^{31} = 3\eta^{012}, \quad d\eta^{12} = -3\eta^{031}.$$

Thus, every oriented hypersurface in a 5-dimensional Einstein-Sasaki manifold has a natural $\{\text{Id}\}$ -structure satisfying (9). By Proposition 5, a one-parameter family of $\{\text{Id}\}$ -structures satisfying (9) is induced on the hypersurface. Conversely, we have the following:

Proposition 6. *Let $(\eta^i(t))$ be a 1-parameter family of $\{\text{Id}\}$ -structures on M such that (9) holds for $t = t_0$. The induced $SU(2)$ -structure on $\mathbf{M} = M \times (t_-, t_+)$ is Einstein-Sasaki if and only if*

$$(10) \quad \begin{cases} \partial_t \eta^0 = 2\eta^1 & \partial_t \eta^{23} = -d\eta^1 \\ \partial_t \eta^{31} = 3\eta^{03} - d\eta^2 & \partial_t \eta^{12} = -3\eta^{02} - d\eta^3 \end{cases}$$

In this case, (9) holds for all t .

Proof. Suppose Equations 10 define an Einstein-Sasaki structure on \mathbf{M} ; then (9) holds for all t . Equations 3 give

$$dt \wedge \partial_t \eta^0 + d\eta^0 = d\alpha = -2\omega_1 = -2\eta^{23} - 2\eta^1 \wedge dt;$$

hence $\partial_t \eta^0 = 2\eta^1$. Moreover

$$d\eta^{31} + dt \wedge \partial_t \eta^{31} + d\eta^2 \wedge dt = d\omega_2 = 3\alpha \wedge \omega_3 = 3\eta^{012} + 3\eta^{03} \wedge dt,$$

and therefore

$$\partial_t \eta^{31} = 3\eta^{03} - d\eta^2;$$

similarly, for ω_3 we get

$$\partial_t \eta^{12} = -3\eta^{02} - d\eta^3.$$

Since (3) implies that ω_1 is closed, we also obtain $d\eta^1 = -\partial_t \eta^{23}$. So the “only if” part is proved.

To prove the “if” part, it suffices to show that (10) forces (9) to hold for all t ; (3) will then follow from the calculations in the first part of the proof. Observe first that

$$\partial_t(d\eta^0 + 2\eta^{23}) = d\partial_t \eta^0 + 2\partial_t \eta^{23} = 0,$$

so the condition $d\eta^0 = -2\eta^{23}$ holds for all t . Using this, we compute

$$\partial_t(d\eta^{12} + 3\eta^{031}) = -3d\eta^{02} - 3\eta^0 \wedge d\eta^2 = -3d\eta^0 \wedge \eta^2 = 6\eta^{23} \wedge \eta^2 = 0$$

and a similar argument shows that all of (9) are preserved in time. \square

Remark. The evolution equations (10) are not in Cauchy-Kowalewsky form. Indeed, write $\eta^i(t) = a_j^i(x, t)\eta^j$, and $d\eta^i = c_{jk}^i \eta^{jk}$, where c_{jk}^i are functions of x . Then (10) reduce to a system of 22 equations in 16 unknowns; so the system is overdetermined. However, it turns out that a solution always exists, at least in the real analytic case, as will be proved elsewhere.

Remark. Given an $\{\text{Id}\}$ -structure satisfying (9), we can define another $\{\text{Id}\}$ -structure satisfying (9) by

$$(11) \quad (\eta^0, \eta^1, \eta^2, \eta^3) \rightarrow (\eta^0, -\eta^1, -\eta^2, -\eta^3) ;$$

this has the effect of reversing the orientation, and reflects the ambiguity in the reduction from \mathbb{Z}_2 to the trivial group. In terms of the evolution equations, this change in orientation corresponds to changing the sign of t .

As an example, consider the Lie group $\text{SU}(2) \times \text{U}(1)$. Fix a basis e^1, e^2, e^3, e^4 of left-invariant 1-forms such that

$$(12) \quad de^1 = -e^{23}, \quad de^2 = -e^{31}, \quad de^3 = -e^{12}, \quad de^4 = 0.$$

One can then define a left-invariant $\{\text{Id}\}$ -structure satisfying (9) by

$$\eta^0 = \frac{1}{3}e^1 + e^4, \quad \eta^1 = e^4, \quad \eta^2 = \frac{1}{\sqrt{6}}e^2, \quad \eta^3 = \frac{1}{\sqrt{6}}e^3.$$

The solution of the evolution equations is:

$$(13) \quad \eta^0 = \frac{1}{3}e^1 + \cos \epsilon t e^4, \quad \eta^1 = -\frac{\epsilon}{2} \sin \epsilon t e^4, \quad \eta^2 = \frac{1}{\epsilon} e^2, \quad \eta^3 = \frac{1}{\epsilon} e^3,$$

where we have set $\epsilon = \sqrt{6}$. The resulting Einstein-Sasaki structure can be extended to a compact 5-manifold, which can be realized as a circle bundle over the Kähler-Einstein manifold $S^2 \times S^2$. Indeed, this is the homogeneous Kobayashi-Tanno metric (see [20]) on the space (1). To see this, let S^3 be another copy of $\text{SU}(2)$, with global invariant forms \tilde{e}^i satisfying relations analogous to (12). We can introduce coordinates θ, ψ, ϕ on S^3 such that

$$(14) \quad \begin{cases} \tilde{e}^1 = -d\psi + \cos \theta d\phi & \tilde{e}^2 = -\sin \psi \sin \theta d\phi + \cos \psi d\theta \\ \tilde{e}^3 = \cos \psi \sin \theta d\phi + \sin \psi d\theta \end{cases}$$

If we set $t = \frac{1}{\epsilon}\theta$ and identify e^4 with $\frac{1}{3}d\phi$, then (13) restricted to $\text{SU}(2) \times \{\psi = 0\}$ becomes

$$(15) \quad \eta^0 = \frac{1}{3}(e^1 + \tilde{e}^1), \quad \eta^1 = -\frac{1}{\epsilon}\tilde{e}^3, \quad \eta^2 = \frac{1}{\epsilon}e^2, \quad \eta^3 = \frac{1}{\epsilon}e^3, \quad dt = \frac{1}{\epsilon}\tilde{e}^2.$$

On the other hand, if viewed as forms on $\text{SU}(2) \times S^3$, the forms (15) annihilate a vector field which we may denote by $e_1 - \tilde{e}_1$, and their Lie derivative with respect to $e_1 - \tilde{e}_1$ is zero; so, they pass onto the quotient. Thus the forms (α, ω_i) defined as in Proposition 5 are invariant under the left action of $\text{SU}(2) \times \text{SU}(2)$, and they define a homogeneous Einstein-Sasaki structure on a homogeneous space equivalent to (1). Notice that this is not a symmetric space.

4. SOLUTIONS ON $\text{SU}(2) \times \text{U}(1)$

In this section we classify solutions of (9) on $G = \text{SU}(2) \times \text{U}(1)$ which are invariant in a certain sense. In order to determine the relevant notion of invariance, let us go back to the hypotheses of Proposition 3. Thus, G acts transitively on a hypersurface $M \subset \mathbf{M}$; let $(\tilde{\eta}^i)$ be the $\{\text{Id}\}$ -structure induced on M by the invariant Einstein-Sasaki structure. Then $(\tilde{\eta}^i)$ pulls back to an $\{\text{Id}\}$ -structure on G which we also denote by $(\tilde{\eta}^i)$. By Lemma 2, L_g^* acts on $\tilde{\eta}^2 + i\tilde{\eta}^3$ as multiplication by $e^{i\gamma}$. So if we set

$$\tilde{\eta}^2 + i\tilde{\eta}^3 = e^{i\gamma}(\eta^2 + i\eta^3),$$

and $\eta^0 = \tilde{\eta}^0, \eta^1 = \tilde{\eta}^1$, then the η^i are left-invariant forms on G .

The Lie algebra of G is $\mathfrak{g} = \mathfrak{su}(2) \oplus \mathfrak{u}(1)$, whose dual will be represented by the basis e^1, \dots, e^4 satisfying (12). Since \mathfrak{g} has only one 3-dimensional subalgebra, the kernel of $e^{i\gamma}$ contains $\mathrm{SU}(2) \times \{1\}$. We can therefore write $d\gamma = me^4$ for some integer m . In terms of the invariant basis (η^i) , Equations 9 become:

$$(16) \quad d\eta^0 = -2\eta^{23}, \quad d\eta^{31} = 3\eta^{012} + me^4 \wedge \eta^{12}, \quad d\eta^{12} = -3\eta^{031} - me^4 \wedge \eta^{31}.$$

Observe that the space of left-invariant solutions of (9) or (16) is closed under right translation. Left-invariant $\{\mathrm{Id}\}$ -structures on G can be identified with $\{\mathrm{Id}\}$ -structures on the Lie algebra \mathfrak{g} , and right translation on G corresponds to the adjoint action of G on \mathfrak{g} . Observe also that replacing $e^{i\gamma}$ with $e^{i(\gamma+A)}$ does not affect (9). Hence solutions of (16) are closed under the transformation

$$(17) \quad (\eta^0, \eta^1, \eta^2, \eta^3) \rightarrow (\eta^0, \eta^1, c\eta^2 + s\eta^3, -s\eta^2 + c\eta^3)$$

where c and s are real constants with $c^2 + s^2 = 1$.

The action of $\mathrm{Int} \mathfrak{g}$ and transformations of type (17), (11) commute; they generate an equivalence relation on the space of solutions.

Proposition 7. *Every invariant solution of (16) on G can be written up to equivalence as either*

$$(18) \quad \eta^0 = 2hk e^1 - \frac{m}{3} e^4, \quad \eta^1 = a e^1, \quad \eta^2 = h e^2, \quad \eta^3 = c e^2 + k e^3,$$

where $h > 0$, $k > 0$, $a > 0$ and c is an arbitrary constant, or

$$(19) \quad \eta^0 = 2h^2 e^1 + \mu e^4, \quad \eta^1 = a_1 e^1 + a_4 e^4, \quad \eta^2 = h e^2, \quad \eta^3 = h e^3,$$

where $h > 0$, $a_4 \neq 0$ and $3a_1\mu = 6h^2a_4 - a_4 - a_1m$.

Proof. Up to an inner automorphism, we can assume that η^0 is in $\langle e^1, e^4 \rangle$. Using (16), we deduce that $\eta^{23} = -\frac{1}{2}d\eta^0$ is a multiple of e^{23} , meaning that

$$\langle \eta^2, \eta^3 \rangle = \langle e^2, e^3 \rangle.$$

Up to a transformation of type (17), we can assume $\eta^2 = h e^2$ for some positive constant h .

Now suppose that η^{31} is closed, and therefore $\eta^1 \in \langle e^1, e^2, e^3 \rangle$. Then (16) gives

$$3\eta^{012} + m e^4 \wedge \eta^{12} = 0.$$

Hence $\eta^0 = -\frac{m}{3}e^4 + qe^1$ and η^1 lies in $\langle e^1, e^2 \rangle$. The same argument applied to $3\eta^{031} + m e^4 \wedge \eta^{31}$ shows that η^1 is a multiple of e^1 , and so (18) holds. Up to changing the signs of both e^1 and e^3 , we can assume $a > 0$. Finally, we can fix the overall orientation to obtain $k > 0$.

Suppose now that η^{31} is not closed, so that

$$\eta^1 = \beta + a_4 e^4, \quad a_4 \neq 0, \quad \beta \in \langle e^1, e^2, e^3 \rangle.$$

By (16), $d\eta^{31} \wedge e^2$ is zero, and therefore $d\eta^3 \wedge e^{42} = 0$, i.e. $\eta^3 = k e^3$ for some constant k . Since we are allowed to change the signs of both e^1 and e^3 , we can assume that k is positive. On the other hand every exact 2-form, as is $d\eta^{31}$, gives zero on wedging with e^4 ; so, by (16) β is in $\langle e^1, e^2 \rangle$. The same argument applied to the last of (16) shows that $\beta = a_1 e^1$ for some constant a_1 .

Now write $\eta^0 = \mu_1 e^1 + \mu_4 e^4$, where $\mu_1 \neq 0$ because η^0 is not closed. Then (16) can be rewritten as

$$hk = \frac{1}{2}\mu_1, \quad -a_4 k = h(3a_1\mu_4 - 3\mu_1 a_4 + a_1 m), \quad -a_4 h = k(3a_1\mu_4 - 3\mu_1 a_4 + a_1 m);$$

the solution is

$$k = h, \quad \mu_1 = 2h^2, \quad 3a_1\mu_4 = 6h^2a_4 - a_4 - a_1m. \quad \square$$

5. THE LOCAL METRICS

In order to give a *local* classification, i.e. classify invariant Einstein-Sasaki structures on non-compact cohomogeneity one manifolds $SU(2) \times U(1) \times (t_-, t_+)$, it is now sufficient to solve the evolution equations (10) using the solutions of Section 4 as initial data. Observe that taking into account the $e^{i\gamma}$ rotation of Lemma 2, we must replace the bottom row of (10) with

$$\partial_t \eta^{31} = 3\eta^{03} - d\eta^2 + d\gamma \wedge \eta^3, \quad \partial_t \eta^{12} = -3\eta^{02} - d\gamma \wedge \eta^2 - d\eta^3.$$

Notice that $e^{i\gamma}$ does not depend on t .

We shall distinguish among three cases.

(i) The first case is given by (19) when $a_1 = 0$. Then $6h^2 - 1 = 0$, and

$$\eta^0 = \frac{1}{3}e^1 + \mu e^4, \quad \eta^1 = a_4 e^4, \quad \eta^2 = \frac{1}{\sqrt{6}}e^2, \quad \eta^3 = \frac{1}{\sqrt{6}}e^3.$$

This family is closed under evolution; explicitly, setting $\epsilon = \sqrt{6}$ for short, the “rotated evolution equations” are solved by

$$\eta^0 = \frac{1}{3}e^1 + \left(k \cos \epsilon t - \frac{m}{3}\right)e^4, \quad \eta^1 = -\frac{k\epsilon}{2} \sin \epsilon t e^4, \quad \eta^2 = \frac{1}{\epsilon}e^2, \quad \eta^3 = \frac{1}{\epsilon}e^3.$$

It is not hard to check that, regardless of k and m , the resulting metric is the Kobayashi-Tanno metric on $V_{2,4}$ described in Section 3.

(ii) The second case is given by (19) when $a_1 \neq 0$. We can set $a_4 = Ca_1$, so that writing a for a_1 :

$$\eta^0 = 2h^2 e^1 + \left(2Ch^2 - \frac{C+m}{3}\right)e^4, \quad \eta^1 = a(e^1 + Ce^4), \quad \eta^2 = h e^2, \quad \eta^3 = h e^3$$

This family is closed under evolution for every choice of C . Indeed, the evolution equations read

$$(20) \quad \frac{d}{dt}h^2 = a, \quad \frac{d}{dt}(ah) = h - 6h^3.$$

which we can rewrite as

$$(2h'h^2)' = -6h^3 + h$$

Fix initial conditions $h(t_0) = h_0$, $a(t_0) = a_0$; we assume that $(\eta^i(t))$ is a well-defined $\{\text{Id}\}$ -structure at $t = t_0$, and therefore $h_0 \neq 0 \neq a_0$. Up to changing the orientation of the 4-manifold — or equivalently, changing the sign of t in (20) — we can assume that $a_0 h_0$ is positive. By continuity and non-degeneracy, $a(t)h(t) > 0$ in (t_-, t_+) . Thus, the first of (20) tells us that $dh/dt > 0$ in (t_-, t_+) . In particular, we can use h as the new variable; writing $x = \frac{dh}{dt}$, (20) gives

$$4x^2 + 2hx \frac{dx}{dh} = 1 - 6h^2.$$

We can solve this differential equation explicitly about h_0 ; the solution is

$$x(h) = \frac{1}{2h^2} \sqrt{A + h^4 - 4h^6},$$

where the sign of the square root has been chosen consistently with $h_0 > 0$, $a_0 > 0$, and A is a constant determined by the initial data. More precisely, by the first of (20)

$$A = 4h_0^6 - h_0^4 + (a_0 h_0)^2 .$$

Since the function $h \rightarrow 4h^6 - h^4$ has $-\frac{1}{108}$ as its minimum and $a_0 h_0 > 0$, it follows that

$$A > -\frac{1}{108} .$$

By the above argument, $h(t)$ is a solution of

$$(21) \quad h'(t) = \frac{1}{2h^2} \sqrt{A + h^4 - 4h^6} ;$$

conversely, it is clear that every solution of (21) gives rise to a solution of (20). However we do not need to solve (21) explicitly: it is sufficient to set

$$(22) \quad \begin{cases} \eta^0 = 2h^2(e^1 + Ce^4) - \frac{C+m}{3}e^4, & \eta^1 = \frac{1}{h}\sqrt{A + h^4 - 4h^6}(e^1 + Ce^4), \\ \eta^2 = he^2, & \eta^3 = he^3, & dt = \frac{2h^2}{\sqrt{A + h^4 - 4h^6}}dh. \end{cases}$$

Whether this metric extends to a compact Einstein-Sasaki 5-manifold depends only on the initial conditions, in a way that we shall determine in Section 7.

(iii) The structure (18) can be rewritten as

$$\eta^0 = 2(hk - bc)e^1 - \frac{m}{3}e^4, \quad \eta^1 = ae^1, \quad \eta^2 = he^2 + be^3, \quad \eta^3 = ce^2 + ke^3,$$

where we can assume that a and $hk - bc$ are positive. We shall also assume that at least one of $h - k$, b and c is non-zero, since otherwise we are reduced to case (ii). This family is closed under evolution: indeed, the evolution equations give

$$(23) \quad \begin{cases} \partial_t(ac) = -6c(hk - bc) - b & \partial_t(ak) = -6k(hk - bc) + h \\ \partial_t(ab) = -6b(hk - bc) - c & \partial_t(ah) = -6h(hk - bc) + k \\ \partial_t(hk - bc) = a \end{cases}$$

Any solution of these equations defines a local Einstein-Sasaki metric, which cannot however be extended to a complete metric, as we shall prove without solving (23) explicitly.

6. EXTENDING TO SPECIAL ORBITS

In Section 5 we have constructed invariant Einstein-Sasaki metrics on $G \times (t_-, t_+)$. The problem remains of determining whether one can extend the resulting Einstein-Sasaki structure to a compact cohomogeneity one manifold with diagram (6). In this section we study this problem in slightly greater generality.

Given a differential form (or, more generally, a tensor) defined away from the special orbits, we want to determine conditions for it to extend to all of \mathbf{M} . By Section 2, this problem reduces to extending a form on $G \times_H (V \setminus \{0\})$ to the zero section. Fix a left-invariant connection on G as a principal bundle over G/H , i.e. a H -invariant one-form $\omega: \mathfrak{g} \rightarrow \mathfrak{h}$ extending the identity on \mathfrak{h} . Then the tangent bundle of $G \times_H V$ can be identified with

$$(G \times V) \times_H \left(\frac{\mathfrak{g}}{\mathfrak{h}} \oplus V \right),$$

where the principal H action on $G \times V$ is given by $(R_h, \rho(h^{-1}))$. Explicitly, the identification is induced by the H -equivariant map

$$(24) \quad T(G \times V) \ni (g, v; A, v') \rightarrow (A_{\mathfrak{g}/\mathfrak{h}}, v' - \omega(A) \cdot v) \in \frac{\mathfrak{g}}{\mathfrak{h}} \oplus V ,$$

where we have used the trivialization of $T(G \times V)$ given by left translation.

A differential form on $G \times_H V$ can be viewed as a H -equivariant map

$$\tau: G \times (V \setminus \{0\}) \rightarrow \Lambda^* \left(\frac{\mathfrak{g}}{\mathfrak{h}} \oplus V \right) ;$$

the form is invariant if the map τ is also G -invariant, i.e. $\tau(gh, v) = \tau(h, v)$. So invariant forms are H -equivariant maps

$$\tau: V \setminus \{0\} \rightarrow \Lambda^* \left(\frac{\mathfrak{g}}{\mathfrak{h}} \oplus V \right) = \Lambda^* \frac{\mathfrak{g}}{\mathfrak{h}} \otimes \Lambda^* V .$$

Now decompose the target space of τ into irreducible H -modules. It is clear that τ extends smoothly across 0 if and only if its components extend. Thus, we only need to determine when an equivariant map

$$\tau: V \setminus \{0\} \rightarrow W$$

extends, where W is an irreducible H -module.

For the rest of this section we shall assume that $H \cong \mathrm{U}(1)$ and $K = \mathbb{Z}_\sigma$ is the cyclic subgroup of order σ ; this is essentially the only situation we will need to consider in this paper. The representations of H are modeled on \mathbb{C} , on which we shall use both polar and Euclidean coordinates, writing the generic element as $x + iy = re^{i\theta}$. More precisely, the non-trivial irreducible representations of H are two-dimensional real vector spaces $V_n \cong \mathbb{C}$, on which $e^{i\theta}$ acts as multiplication by $e^{in\theta}$. We have

$$V_n \otimes V_m = V_{n-m} \oplus V_{n+m} .$$

The $\mathrm{U}(1)$ -space $V_\sigma \cong \mathbb{C}$ has a canonical section $[0, +\infty) \subset \mathbb{C}$, and any equivariant map from V_σ to V_n is determined by its restriction to this section.

Proposition 8 (Kazdan-Warner). *A non-zero smooth map*

$$\tau: [0, +\infty) \rightarrow V_n$$

extends to a smooth equivariant map defined on all of V_σ if and only if σ divides n and the k -th derivative of τ at zero vanishes for

$$k = 0, 1, \dots, \left\lfloor \frac{n}{\sigma} \right\rfloor - 1, \left\lfloor \frac{n}{\sigma} \right\rfloor + 1, \left\lfloor \frac{n}{\sigma} \right\rfloor + 3 \dots$$

Proof. Set $m = n/\sigma$. The equivariant extension of τ to $\mathbb{R} \subset V_\sigma$ must satisfy

$$\tau(-r) = (-1)^m \tau(r) ,$$

implying that m is integer. We need this extension to be smooth, which is equivalent to requiring that the odd derivatives at zero vanish if m is even, and the even derivatives vanish if m is odd. The equivariant extension of τ to V_σ is given in polar coordinates by

$$f(r, \theta) = \tau(re^{i\theta}) = e^{im\theta} \tau(r) .$$

Set $\tilde{f}(r \cos \theta, r \sin \theta) = f(r, \theta)$. If \tilde{f} is smooth at the origin, then

$$r^k e^{im\theta} \frac{d^k \tau}{dr^k}(0) = r^k \frac{\partial^k}{\partial r^k} f(0, \theta) = r^k \sum_{h=0}^k \cos^h \theta \sin^{k-h} \theta \frac{\partial \tilde{f}}{\partial x^h \partial y^{k-h}}(0, 0)$$

is a homogeneous polynomial of degree k in $r \cos \theta$, $r \sin \theta$. This condition is also sufficient for \tilde{f} to be smooth [17]. On the other hand, it is easy to check that $r^k e^{im\theta}$ is not a homogeneous polynomial of degree k unless $k - |m|$ is even and non-negative. \square

We now illustrate the method in the case of $G = \mathrm{SU}(2) \times \mathrm{U}(1)$. On the Lie algebra of G , fix a basis e_1, \dots, e_4 such that the dual basis satisfies (12). If we identify $\mathrm{SU}(2)$ with unit quaternions and its Lie algebra with imaginary quaternions, our choice can be expressed as

$$e_1 = i/2, \quad e_2 = j/2, \quad e_3 = k/2.$$

In particular, we see from this that e_1 has period 4π . Let H be the connected subgroup of G with Lie algebra spanned by

$$\xi = pe_1 + qe_4,$$

where $p/2$ and q are coprime integers. Then ξ has period 2π , and we can identify H with $\mathrm{U}(1)$. The adjoint action of H on \mathfrak{g}^* is trivial on $\langle e^1, e^4 \rangle$, and so its action is determined by

$$e^{i\theta} \cdot e^2 = \cos p\theta e^2 + \sin p\theta e^3, \quad e^{i\theta} \cdot e^3 = -\sin p\theta e^2 + \cos p\theta e^3.$$

So, for instance, the space of G -invariant 2-forms is identified with the space of $\mathrm{U}(1)$ -invariant maps from V_σ to

$$\Lambda^2(V_p \oplus V_\sigma \oplus \mathbb{R}) \cong V_0 \oplus V_{p+\sigma} \oplus V_{p-\sigma} \oplus V_p \oplus V_\sigma.$$

More explicitly, fix the connection form

$$\frac{1}{p^2 + q^2} (pe^1 + qe^4),$$

where we have used ξ to identify \mathfrak{h} with \mathbb{R} . This choice determines a horizontal space $\mathfrak{h}^\perp = \langle qe_1 - pe_4, e_2, e_3 \rangle$, and realizes the identification map (24) as

$$\begin{aligned} (\mathrm{Id}, r; A, v') &\rightarrow (A, v'), \quad A \in \mathfrak{h}^\perp \\ (\mathrm{Id}, r; pe_1 + qe_4, v') &\rightarrow (0, v' - \sigma r \partial / \partial y) \end{aligned}$$

By duality, we see that:

- the 1-forms e^2, e^3 and $qe^1 - pe^4$ are mapped to the corresponding elements of $(\mathfrak{g}/\mathfrak{h})^*$;
- the connection form is mapped to $-\frac{1}{\sigma r} dy$.

This is all one needs to know in order to translate a differential form (or a tensor) into an equivariant map τ , and apply the criterion of Proposition 8.

7. FROM LOCAL TO GLOBAL

We can now apply the criteria from Section 6 to determine conditions for the local metrics of Section 5 to extend smoothly across the special orbits. Consider the one-parameter family of $\{\mathrm{Id}\}$ -structures

$$(25) \quad \begin{cases} \eta^0 = 2\Delta(e^1 + Ce^4) - \frac{C+m}{3}e^4, & \eta^1 = \Delta'(e^1 + Ce^4), \\ \eta^2 = he^2 + be^3, & \eta^3 = ce^2 + ke^3, \end{cases}$$

where we have set

$$\Delta = hk - bc,$$

and we assume the constant $C + m$ and the functions $\Delta(t)$, $\Delta'(t)$ to be non-zero in the interval (t_-, t_+) . In particular, solutions of the evolution equations (22) or (23) are of this form. Recall from Proposition 3 that the principal stabilizer K is contained in a torus T^2 ; by the expression of (25), it follows that the Lie algebra of T^2 is spanned by e_1 and e_4 .

We introduce the variables

$$r_{\pm} = \pm(t_{\pm} - t) ,$$

so that the special orbit G/H_{\pm} corresponds to $r_{\pm} = 0$. For brevity's sake, we shall drop the subscript sign and simply write H , r rather than H_{\pm} , r_{\pm} . We shall refer to the point $r = 0$ as the origin, and say that a function $f(r)$ on $[0, \epsilon)$, $\epsilon > 0$ is odd (resp. even) at the origin if it extends to a smooth odd (resp. even) function on $(-\epsilon, \epsilon)$. We can now determine conditions on the functions h , k , b , c , and Δ in order that the metric extend smoothly across each special orbit.

Lemma 9. *The one-parameter family of $\{\text{Id}\}$ -structures (25) defines an invariant $U(2)$ -structure on the cohomogeneity one manifold $G \times (t_-, t_+)$. If this structure extends across the special orbit G/H , then*

- $H_0 = \text{SU}(2) \times \{1\}$, $\frac{1}{r^4}(hb + ck)$ is even, and

$$\Delta/r^2, \quad \frac{1}{r^2}(h^2 + c^2), \quad \frac{1}{r^2}(k^2 + b^2)$$

are even functions, all taking the value $\frac{1}{4}$ at the origin; or

- $H_0 \cong U(1)$, with Lie algebra $\mathfrak{h} = \langle pe_1 + qe_4 \rangle$, where $p/2$ and q are coprime integers satisfying $p + qC > 0$;

$$\Delta, \quad h^2 + c^2 + b^2 + k^2$$

are even functions satisfying

$$|\Delta''(0)| = \frac{\sigma}{p + qC}, \quad \Delta(0) = \frac{q(C + m)}{6(p + qC)} \neq 0 ,$$

where σ is the order of $K \cap H_0$, and $hk + bc$, $h^2 + c^2 - b^2 - k^2$ are smooth functions that, if $p \neq 0$, vanish at the origin.

The first condition is also sufficient, whereas the second one becomes sufficient if $hk + bc$ and $h^2 + c^2 - b^2 - k^2$ are identically zero.

Proof. We think of a $U(2)$ -structure as defined by a 1-form α , a 2-form ω_1 and a Riemannian metric g ; the $U(2)$ -structure extends across a special orbit if and only if these tensors extend smoothly, while remaining non-degenerate. Assume first that H has dimension three. By the final remarks of Section 2, the identity component of H is the subgroup $\text{SU}(2) \times \{1\}$, and the normal bundle at G/H is given by (7). Thus, V is the 4-dimensional irreducible representation of $\text{SU}(2)$ and

$$G \times_H V \cong V \times U(1) .$$

In particular we can identify $G/K \times (t_-, t_+)$ with an open set in $V \times U(1)$. Explicitly, we define V to be the field of quaternions, identifying $\text{SU}(2)$ with the unit sphere in V , acting on the left.

We write the generic element of V as $x^0 + x^1i + x^2j + x^3k$, and identify r with the radial coordinate

$$r = \sqrt{(x^0)^2 + (x^1)^2 + (x^2)^2 + (x^3)^2} .$$

Then

$$\begin{aligned} e^1 &= \frac{2}{r^2} (x^0 dx^1 - x^1 dx^0 - x^2 dx^3 + x^3 dx^2) \\ e^2 &= \frac{2}{r^2} (x^0 dx^2 + x^1 dx^3 - x^2 dx^0 - x^3 dx^1) \\ e^3 &= \frac{2}{r^2} (x^0 dx^3 - x^1 dx^2 + x^2 dx^1 - x^3 dx^0) \\ \mp dt &= \frac{1}{r} (x^0 dx^0 + x^1 dx^1 + x^2 dx^2 + x^3 dx^3) \end{aligned}$$

where the sign of $\mp dt$ depends on the special orbit G/H_{\pm} we consider, and the coefficient 2 is a consequence of our choice (12). Rewriting in these terms the 2-form

$$\omega_1 = \Delta'(e^1 + Ce^4) \wedge dt + \Delta e^{23},$$

we see that ω_1 is smooth and non-degenerate at the origin only if $\Delta' \sim \mp \frac{2\Delta}{r}$, so that

$$\omega_1 \sim \frac{2\Delta}{r^2} (2dx^2 \wedge dx^3 - 2dx^0 \wedge dx^1 + Ce^4 \wedge (x^0 dx^0 + x^1 dx^1 + x^2 dx^2 + x^3 dx^3)).$$

Hence, Δ/r^2 is even and non-zero at the origin. In particular α is smooth, and it does not vanish at G/H since $C + m \neq 0$. Moreover $\Delta(0) = 0 = \Delta'(0)$. The rest of the statement now follows from the fact that the metric tensor $dt \otimes dt + \sum_i \eta^i \otimes \eta^i$ has the form

$$\begin{aligned} (4\Delta^2 + (\Delta')^2) e^1 \otimes e^1 &+ \left(\left(2C\Delta - \frac{C+m}{3} \right)^2 + (C\Delta')^2 \right) e^4 \otimes e^4 + \\ &+ \left(C(\Delta')^2 + 2\Delta \left(2C\Delta - \frac{C+m}{3} \right) \right) e^1 \odot e^4 + (h^2 + c^2) e^2 \otimes e^2 + \\ &+ (k^2 + b^2) e^3 \otimes e^3 + (hb + ck) e^2 \odot e^3 + dt \otimes dt \end{aligned}$$

and thus smoothness requires

$$4\Delta^2 + (\Delta')^2 \sim h^2 + c^2 \sim k^2 + b^2 \sim \frac{1}{4} r^2.$$

Now suppose H is one-dimensional, so that $H_0 \cong \text{U}(1)$. Then Δ is non-zero at the origin. Indeed, assuming otherwise, we shall prove that α is not smooth. In general, we are not allowed to replace H with H_0 , since a smooth invariant form on $G \times_{H_0} V$ does not necessarily correspond to a smooth form on $G \times_H V$. However, the converse always holds. Thus, we can apply the language of Section 6 in order to prove that α is not smooth. Let the Lie algebra of H_0 be spanned by

$$\xi = pe_1 + p'e_2 + p''e_3 + qe_4.$$

The connection form corresponding to H_0 has the form

$$\frac{pe^1 + p'e^2 + p''e^3 + qe^4}{p^2 + (p')^2 + (p'')^2 + q^2}.$$

Since $\alpha(\xi) = 2p\Delta + q(2C\Delta - \frac{C+m}{3})$, we can write

$$\alpha \equiv -\frac{1}{\sigma r} \left(2p\Delta + q \left(2C\Delta - \frac{C+m}{3} \right) \right) dy \pmod{(\mathfrak{g}/\mathfrak{h})^*},$$

So if $\Delta(0)$ were zero, then α could only be smooth if $C + m = 0$, which is absurd.

Having shown that $\Delta(0) \neq 0$, we can conclude that the isotropy representation of H fixes e^1 , and so H is contained in T^2 . Recall from Section 2 that this condition ensures that (7) holds; so, it is now safe to replace H with H_0 .

Let the Lie algebra of H be generated by $\xi = pe_1 + qe_4$, where $\frac{p}{2}$ and q are coprime integers. Write

$$\alpha = -\frac{1}{\sigma r} \left(2p\Delta + q \left(2C\Delta - \frac{C+m}{3} \right) \right) dy + \left(2q\Delta - p \left(2C\Delta - \frac{C+m}{3} \right) \right) \frac{qe^1 - pe^4}{p^2 + q^2}$$

By Proposition 8, α is smooth if and only if

$$2(p + qC)\Delta(0) - \frac{q(C+m)}{3} = 0, \quad \Delta \text{ is even.}$$

Write

$$\omega_1 = (p + qC) \frac{\Delta'}{\sigma r} dx \wedge dy + \Delta'(q - pC) \frac{qe^1 - pe^4}{p^2 + q^2} \wedge dx + \Delta e^{23}.$$

We already know that $\Delta(r)$ is even; hence,

$$\Delta'(r) = \frac{d\Delta}{dt}(r) = \mp \frac{d\Delta}{dr}(r)$$

is odd, implying that ω_1 is smooth. On the other hand, requiring that ω_1 be non-degenerate gives

$$\Delta''(0) \neq 0, \quad p + qC \neq 0.$$

Replacing ξ with $-\xi$ if necessary, we can assume that $p + qC$ is positive. The metric tensor can be decomposed as

$$\begin{aligned} dx \otimes dx + s(dy \otimes dy) + f \left(dy \odot \frac{qe^1 - pe^4}{p^2 + q^2} \right) + g \left(\frac{qe^1 - pe^4}{p^2 + q^2} \right)^2 + \\ + (h^2 + c^2)(e^2 \otimes e^2) + (b^2 + k^2)(e^3 \otimes e^3) + (hb + ck)e^2 \odot e^3 \end{aligned}$$

whence

$$s = \frac{1}{\sigma^2 r^2} \left(\left(2(p + qC)\Delta - \frac{q(C+m)}{3} \right)^2 + (p + qC)^2 (\Delta')^2 \right)$$

must be even and $s(0) = 1$. The former condition is automatic, whereas the latter gives

$$|\Delta''(0)| = \frac{\sigma}{p + qC}.$$

Moreover f must be odd, g must be even, and $g, h^2 + k^2 + c^2 + b^2$ must be non-zero at the origin; all these conditions follow from those we have already obtained. The rest of the statement follows from the fact that $e^2 \otimes e^2 + e^3 \otimes e^3$ is H -invariant, whereas

$$\langle e^2 \odot e^3, e^2 \otimes e^2 - e^3 \otimes e^3 \rangle$$

is isomorphic to V_{2p} . □

We can now prove the main result of this section. We shall use the identification

$$T^2 = \{(\exp 2\theta e_1, \exp \psi e_4) \in \text{SU}(2) \times \text{U}(1)\} \cong \{(e^{i\theta}, e^{i\psi}) \in \text{U}(1) \times \text{U}(1)\}.$$

Theorem 10. *There is no solution of (23) that defines an Einstein-Sasaki metric on a compact manifold. The Einstein-Sasaki structure (22) extends to an invariant Einstein-Sasaki structure on the compact cohomogeneity one manifold with diagram (6) if and only if:*

- $A = 0$, K is a finite subgroup of T^2 intersecting $(H_+)_0$ in a group of order σ ,

$$H_+ = \left\{ \left(e^{\frac{1}{2}(\sigma+mq)i\theta}, e^{qi\theta} \right) \in T^2, \theta \in \mathbb{R} \right\} \cdot K, \\ H_- = (\text{SU}(2) \times \{1\}) \cdot K,$$

where q and $\frac{1}{2}(qm + \sigma)$ are coprime integers, and $\sigma = -\frac{1}{3}(C + m)q$. The resulting Riemannian manifold is locally isometric to S^5 .

- $A < 0$, K is a finite subgroup of T^2 intersecting $(H_{\pm})_0$ in a group of order σ_{\pm} ;

$$H_{\pm} = \left\{ \left(e^{\frac{1}{2}(\sigma_{\pm}+mq_{\pm})i\theta}, e^{q_{\pm}i\theta} \right) \in T^2, \theta \in \mathbb{R} \right\} \cdot K,$$

where q_{\pm} and $\frac{1}{2}(q_{\pm}m + \sigma_{\pm})$ are coprime integers, and the equation

$$(26) \quad A + \Delta^2 - 4\Delta^3 = 0$$

has two distinct roots Δ_- , Δ_+ such that

$$\frac{q_{\pm}}{\sigma_{\pm}} = \frac{1}{C+m} \frac{6\Delta_{\pm}}{1-6\Delta_{\pm}}.$$

Then the Einstein-Sasaki structure is quasi-regular if C is rational, and irregular otherwise.

Proof. In (23), we can assume that at some $t = t_0$

$$h, k, \Delta' > 0, \quad b = 0, \quad (k - h, c) \neq (0, 0).$$

Introduce the variables

$$u = h + k, \quad v = h - k, \quad z = b + c, \quad w = b - c;$$

by above, either $u, v \neq 0$ at $t = t_0$ or we can apply a transformation of type (17) to obtain $u, v \neq 0$. Then about t_0 (23) reads

$$(27) \quad \Delta'' + 6\Delta = -1 - \Delta' \frac{z'}{z} = 1 - \Delta' \frac{w'}{w} = 1 - \Delta' \frac{u'}{u} = -1 - \Delta' \frac{v'}{v}$$

Every solution of (27) satisfies $w = \lambda u$ and $z = \mu v$, where λ and μ are constants. Thus

$$\Delta = \frac{1}{4}(u^2 - v^2 - z^2 + w^2) = \left(\frac{1+\lambda^2}{4} \right) u^2 - \left(\frac{1+\mu^2}{4} \right) v^2.$$

This motivates us to set $U = \frac{\sqrt{1+\lambda^2}}{2}u$, $V = \frac{\sqrt{1+\mu^2}}{2}v$, transforming (27) into

$$(28) \quad \Delta'' + 6\Delta = 1 - \Delta' \frac{U'}{U} = -1 - \Delta' \frac{V'}{V}, \quad \Delta' = \frac{2}{\frac{U'}{U} - \frac{V'}{V}}, \quad \Delta = U^2 - V^2.$$

These equations only make sense at points where $U, V \neq 0$. However, U cannot vanish in (t_-, t_+) because Δ is positive, and if V were zero at some t_0 in (t_-, t_+) then it would be zero on all the interval, as one can see by applying a transformation of type (17) and reducing to case (ii) of Section 5.

Suppose that H is one-dimensional. Since $C = 0$, Lemma 9 implies that $p > 0$, and

$$hb + ck = \frac{1}{2}(\lambda + \mu)uv, \quad h^2 + c^2 - b^2 - k^2 = (1 - \lambda\mu)uv$$

must vanish at the origin. So, $U(0)V(0) = 0$. Since, again by Lemma 9, Δ is a smooth function with $\Delta(0) > 0$, it follows that $V(0) = 0$, $U(0) \neq 0$. Now observe that

$$(29) \quad h^2 + k^2 + b^2 + c^2 = 4V^2 + 2\Delta = 4U^2 - 2\Delta ,$$

is even by Lemma 9, so that U^2 and V^2 are also even. This implies that U, V are smooth functions, and U'/U vanishes at 0. By (28), it follows that

$$\lim_{r \rightarrow 0} \frac{V'}{V} = \lim_{r \rightarrow 0} - \left(\frac{U'}{U} - \frac{V'}{V} \right) = \lim_{r \rightarrow 0} - \frac{2}{\Delta'} = -\infty .$$

On the other hand, since $V(r)$ is non-zero for all $r > 0$ we have

$$\lim_{r \rightarrow 0} \frac{dV}{dr} \geq 0 .$$

Since $dr = \mp dt$, we conclude that this possibility may only occur at t_+ .

Suppose now that H has dimension three. Then Lemma 9 and (29) imply that $V^2/r^2, U^2/r^2$ are even. Dividing (29) by r^2 and evaluating at the origin, we find $U^2/r^2 = \frac{1}{4}$, $V^2/r^2 = 0$ at the origin. It follows from (28) and Lemma 9 that

$$\frac{1}{2} = -1 - \lim_{r \rightarrow 0} \Delta' \frac{V'}{V} = -1 \pm \frac{1}{2} \lim_{r \rightarrow 0} \frac{rV'}{V}$$

and so we reach the contradiction

$$0 \leq \lim_{r \rightarrow 0} \frac{r \frac{dV}{dr}}{V} = \mp \lim_{r \rightarrow 0} \frac{rV'}{V} = -3 .$$

This completes the proof of the first part of the theorem.

Now consider a solution of (22). By Lemma 9, at the origin either $h = 0$ or $(h^2)' = 0$. The first possibility can only occur if $A = 0$. In this case, (21) gives

$$h' = \sqrt{\frac{1}{4} - h^2} ,$$

and thus $\Delta = h^2$ is a smooth even function such that $\Delta''(0) = \frac{1}{2}$. Then, by Lemma 9, $H_0 = \text{SU}(2) \times \{1\}$ and the structure extends across G/H . Notice that one cannot have $h = 0$ at both special orbits, because otherwise h' would have to vanish at some point in between. On the other hand, h' vanishes at both special orbits if and only if A is negative.

Suppose that $h' = 0$ at the origin. It follows from (21) that Δ is automatically even, and Lemma 9 only requires that, at the origin,

$$\Delta = \frac{q(C+m)}{6(p+qC)}, \quad \frac{\sigma}{p+qC} = |1-6\Delta| ,$$

where we have used a formula analogous to (27) to express Δ'' in terms of Δ . Since σ is determined up to sign, we can write

$$(30) \quad q = \frac{\sigma}{C+m} \frac{6\Delta(0)}{1-6\Delta(0)} , \quad p = qm + \sigma .$$

The condition $h' = 0$ means that $\Delta(0)$ is a root of (26).

Thus, if $A = 0$, $\Delta(t_+) = \frac{1}{4}$ and (30) gives

$$q = -\frac{3\sigma}{C+m} ;$$

the remaining conditions on p , q and σ follow from Lemma 9. A straightforward computation shows that the Riemannian metric has constant sectional curvature, and therefore the Riemannian manifold we obtain is locally isometric to S^5 .

If A is non-zero, both special orbits are three-dimensional and satisfy (30), which together with Lemma 9 determines the required conditions. Finally, the statement about regularity follows from the fact that the characteristic vector field is $Ce_1 - e_4$, up to an invariant function. \square

It was proved in [13] that there are countably infinite values of A in the interval $-\frac{1}{108} < A < 0$ for which (26) has roots Δ_+ , Δ_- with $\Delta_+ - \Delta_- \in \mathbb{Q}$. One can show, using (26), that for any such value of A and any choice of m there exists a value of C satisfying the hypotheses of Theorem 10. Moreover, there also exist infinite values of A for which both Δ_+ and Δ_- are rational, so that C is also rational and the metric is quasi-regular.

Remark. It follows from (22) that the right action of T^2 on G preserves the $U(2)$ -structure. One can then replace G with a subgroup

$$SU(2) \times U(1) \subset G \times T^2$$

that acts transitively on G preserving the Einstein-Sasaki $SU(2)$ -structure. Since $T^2 \supset K$, H_{\pm} is abelian, this action is well defined on the cohomogeneity one manifold (6). Thus, we discover that the cohomogeneity one action can be assumed to preserve the $SU(2)$ -structure, which amounts to setting $m = 0$ in (22).

By the above remark, there is no loss of generality in assuming $m = 0$. Thus, we recover the Einstein-Sasaki metrics of [13]. Indeed, introduce coordinates (θ, ψ, ϕ) on $SU(2) = S^3$ as in (14), a coordinate α on $U(1)$ such that $e^4 = d\alpha$, and a coordinate y on (t_-, t_+) such that $y = 1 - 6\Delta$. Set

$$\beta = -\psi + C\alpha, \quad wq = \left(\frac{2(108A + 1 - 3y^2 + 2y^3)}{1 - y} \right).$$

Then our family of local Einstein-Sasaki metrics can be written as

$$\begin{aligned} \frac{1-y}{6}(d\theta^2 + \sin^2\theta d\phi^2) + \frac{1}{wq}dy^2 + \frac{1}{36}wq(d\beta + \cos\theta d\phi)^2 + \\ + \frac{1}{9}(d\psi - \cos\theta d\phi + y(d\beta + \cos\theta d\phi))^2 \end{aligned}$$

which is the local form of a $Y^{p,q}$ metric if $A < 0$, and the standard metric on the sphere if $A = 0$.

8. CLASSIFICATION

We can finally prove that the only cohomogeneity one Einstein-Sasaki 5-manifolds are the $Y^{p,q}$.

Theorem 11. *Let \mathbf{M} be a compact, simply-connected Einstein-Sasaki 5-manifold on which the group of isometries acts with cohomogeneity one. Then \mathbf{M} can be represented by the diagram (6), where*

$$\begin{aligned} K &= \left\langle (-1, e^{2\pi i q_+ / \sigma_+}), (-1, e^{2\pi i q_- / \sigma_-}) \right\rangle \subset T^2, \\ H_{\pm} &= \left\{ \left(e^{\frac{1}{2}\sigma_{\pm} i \theta}, e^{q_{\pm} i \theta} \right) \in T^2, \theta \in \mathbb{R} \right\} \cdot K, \end{aligned}$$

the integers q_{\pm}, σ_{\pm} satisfy Theorem 10, and the metric is given by (22). Moreover, \mathbf{M} is diffeomorphic to $S^2 \times S^3$.

Proof. Since the group of isometries of S^5 acts in a homogeneous way, \mathbf{M} is not isometric to S^5 . Thus, by Theorem 10 and the subsequent remark \mathbf{M} can be represented by the diagram $\tilde{K} \subset \tilde{H}_{\pm} \subset G$, where \tilde{K} is a finite subgroup of T^2 intersecting $(\tilde{H}_{\pm})_0$ in a group of order σ_{\pm} , and

$$\tilde{H}_{\pm} = \left\{ \left(e^{\frac{1}{2}\sigma_{\pm}i\theta}, e^{q_{\pm}i\theta} \right) \in T^2, \theta \in \mathbb{R} \right\} \cdot \tilde{K}.$$

Now define K, H_{\pm} as in the statement; then $\tilde{H}_{\pm}/H_{\pm} \cong \tilde{K}/K$. Thus, up to an equivariant covering map \mathbf{M} is represented by the diagram $K \subset H_{\pm} \subset G$. Since \mathbf{M} is simply connected, this covering map is actually a diffeomorphism.

Recall from Section 2 that the diagram determines \mathbf{M} only up to a glueing map. However, in our case K is contained in the center of G , and so the diagram does determine \mathbf{M} up to equivariant diffeomorphism.

To determine the topology of \mathbf{M} , we make use of Smale's classification theorem [19]; indeed, the existence of an Einstein-Sasaki metric implies that \mathbf{M} is spin, whence it suffices to prove that

$$H_2(\mathbf{M}) = \mathbb{Z}, \quad \pi_1(\mathbf{M}) = 0.$$

Let D_{\pm} be the 2-dimensional disc, and write $\mathbf{M} = U_+ \cup U_-$, where $U_{\pm} = G \times_{H_{\pm}} D_{\pm}$. Then G/H_{\pm} is a retract of U_{\pm} , whereas G/K is a retract of $U_+ \cap U_-$. Define loops $\gamma_4, \gamma_{\pm} : S^1 \rightarrow G$ by

$$\gamma_4(e^{it}) = \exp(te_4), \quad \gamma_{\pm}(e^{it}) = \exp(t\sigma_{\pm}e_1 + tq_{\pm}e_4).$$

It is not difficult to show that

$$\begin{aligned} \pi_1(G/K) &= \frac{\mathbb{Z}\gamma_+ \oplus \mathbb{Z}\gamma_- \oplus \mathbb{Z}\gamma_4}{\langle \sigma_+ \gamma_+ - q_+ \gamma_4, \sigma_- \gamma_- - q_- \gamma_4 \rangle}, \\ \pi_1(G/H_{\pm}) &= \frac{\mathbb{Z}\gamma_- \oplus \mathbb{Z}\gamma_4}{\langle \sigma_{\mp} \gamma_{\mp} - q_{\mp} \gamma_4, q_{\pm} \gamma_4 \rangle}, \quad H_2(G/H_{\pm}) = 0. \end{aligned}$$

By the Van-Kampen theorem, it follows that

$$\pi_1(\mathbf{M}) = \frac{\mathbb{Z}\gamma_4}{\langle q_+ \gamma_4, q_- \gamma_4 \rangle},$$

and so \mathbf{M} is simply connected if and only if q_+ and q_- are coprime. On the other hand the Mayer-Vietoris sequence gives

$$H_2(U_+) \oplus H_2(U_-) \longrightarrow H_2(M) \longrightarrow H_1(U_+ \cap U_-) \xrightarrow{j} H_1(U_+) \oplus H_1(U_-)$$

By above, we conclude

$$H_2(\mathbf{M}) \cong \ker j = \mathbb{Z}(q_+ q_- \gamma_4) \cong \mathbb{Z},$$

where we have used the fact that q_+ and q_- are coprime. \square

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DIPARTIMENTO DI MATEMATICA E APPLICAZIONI, UNIVERSITÀ DI MILANO BICOCCA, VIA COZZI
53, 20125 MILANO, ITALY
E-mail address: diego.conti@unimib.it